

BMS Series

DC-Brushless Torque Motors

Slotless, brushless stator design provides zero-cogging torque for unsurpassed velocity control

Smoother velocity than with standard DC brush-type motors with the advantage of reliable brushless technology

Standard NEMA frame sizes

Ultra-high resolution capability with amplified sine-wave encoder and multiplier



Aerotech's BMS series brushless, slotless servomotors represent the ultimate in high-performance rotary motors. Available in standard NEMA frame sizes, these motors utilize a slotless rotor design for superior velocity smoothness and control.

Featuring rare-earth neodymium iron boron magnets and a high pole-count rotor, the BMS series provides maximum torque and acceleration in a small package. Custom mechanical or electrical variations of the BMS can be engineered with minimal lead time.

Smoother than DC Motors

The BMS series motors can replace standard brushless or brush-type motors when superior velocity smoothness and control are required. DC brush-type motors have been popular in applications such as machine tool and scanning because of their smooth low-speed control. The BMS motors provide superior smoothness and have higher acceleration capability than a DC brush motor. Higher acceleration results in higher machine throughput and performance.

High Performance Design

The BMS series is unlike conventional brushless servomotors because it incorporates a totally slotless stator design that provides the ultimate in smooth velocity control. These motors are designed for applications requiring superior torque and stability performance. The unique design of the BMS series motors provides a closer inertia match with mechanical systems than comparable models. This means better stability and easier tuning.

Ultra-High Encoder Resolution

The BMS series motors can be equipped with a variety of encoder resolution options for any application. In addition to the standard RS-422 line driver output, an optional amplified sine-wave encoder can be used to provide ultra-high resolution. Aerotech offers encoder multipliers as an option for drives connected to the A3200 system, as well as external multiplier boxes. Resolutions as high as 1,000,000 counts per revolution are achievable.

BMS Series SPECIFICATIONS

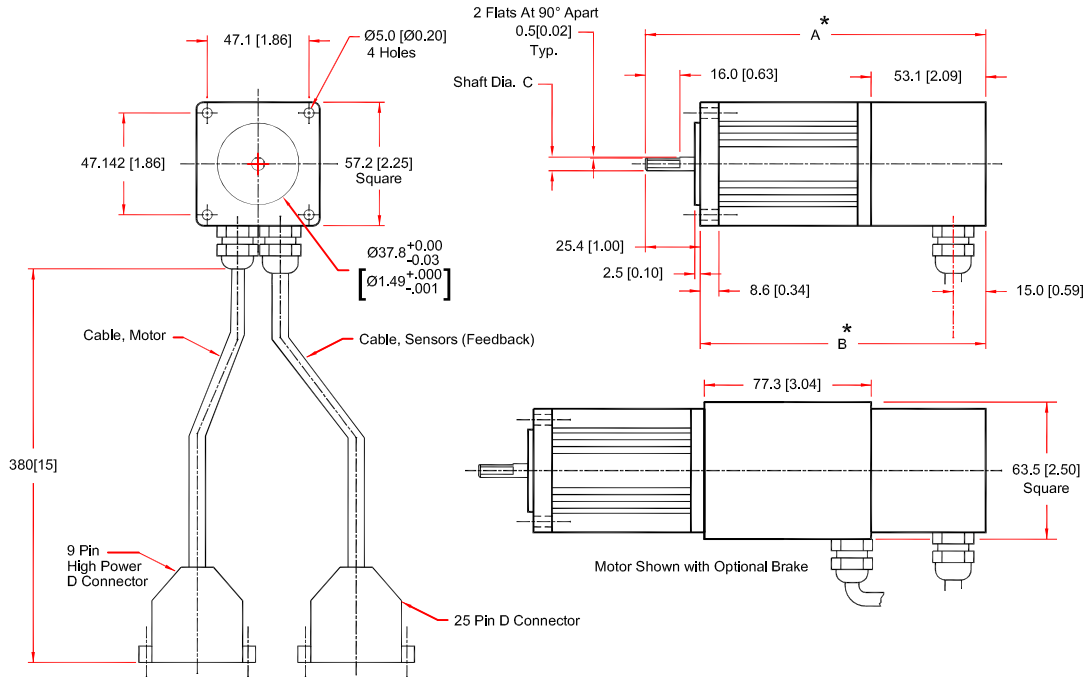
| Model | | BMS60 | BMS100 | BMS280 | BMS465 |
|--|---------------------------|-----------------------|-----------------------|-----------------------|-----------------------|
| Winding Designation | | -A | -A | -A | -A |
| Performance Specifications (1,5) | | | | | |
| Stall Torque, Continuous⁽²⁾ | N-m | 0.33 | 0.56 | 1.60 | 2.86 |
| | oz-in | 46.2 | 80.0 | 227.0 | 404.8 |
| Peak Torque⁽³⁾ | N-m | 1.31 | 2.26 | 6.41 | 11.43 |
| | oz-in | 184.9 | 320.0 | 908.0 | 1619.2 |
| Rated Speed | rpm | 4,000 | 3,000 | 3,000 | 2,000 |
| Rated Power Output, Continuous | watts | 112 | 133 | 381 | 457 |
| Electrical Specifications⁽⁵⁾ | | | | | |
| BEMF Constant (line to line, max) | Volts _{pk} /krpm | 19 | 40 | 57 | 79 |
| Continuous Current, Stall⁽²⁾ | Amp _{pk} | 2.3 | 2.1 | 3.8 | 4.9 |
| | Amp _{rms} | 1.6 | 1.5 | 2.7 | 3.5 |
| Peak Current, Stall⁽³⁾ | Amp _{pk} | 9.2 | 8.4 | 15.2 | 19.6 |
| | Amp _{rms} | 6.5 | 5.9 | 10.7 | 13.9 |
| Torque Constant^(4,8) | N-m /Amp _{pk} | 0.14 | 0.27 | 0.42 | 0.58 |
| | oz-in /Amp _{pk} | 20.1 | 38.1 | 59.7 | 82.6 |
| | N-m /Amp _{rms} | 0.20 | 0.38 | 0.60 | 0.82 |
| | oz-in /Amp _{rms} | 28.4 | 53.9 | 84.5 | 116.8 |
| Motor Constant^(2,4) | N-m/√W | 0.050 | 0.076 | 0.179 | 0.280 |
| | oz-m/√W | 7.02 | 10.74 | 25.34 | 39.70 |
| Resistance, 25°C (line to line) | ohms | 8.4 | 12.9 | 5.7 | 4.4 |
| Inductance (line to line) | mH | 1.30 | 2.40 | 1.10 | 0.87 |
| Maximum Bus Voltage | VDC | 340 | 340 | 340 | 340 |
| Thermal Resistance | C/W | 1.73 | 1.35 | 0.93 | 0.72 |
| Number of Poles | P | 8 | 8 | 14 | 14 |
| Mechanical Specifications | | | | | |
| Motor Weight | kg | 1.1 | 1.5 | 3.60 | 5.00 |
| | lb | 2.4 | 3.3 | 7.9 | 11.0 |
| Rotor Moment of Inertia | kg-m ² | 1.96x10 ⁻⁵ | 3.71x10 ⁻⁵ | 4.66x10 ⁻⁴ | 9.28x10 ⁻⁴ |
| | oz-in-s ² | 0.0028 | 0.0053 | 0.0660 | 0.1314 |
| Max. Radial Load | N | 89 | 89 | 178 | 178 |
| | lb | 20 | 20 | 40 | 40 |
| Max. Axial Load | N | 89 | 89 | 89 | 89 |
| | lb | 20 | 20 | 20 | 20 |

Notes:

- Performance is dependent upon heat sink configuration, system cooling conditions, and ambient temperature.
- Values shown @ 75°C rise above a 25°C ambient temperature, with housed motor mounted to a 250 mm x 250 mm x 6 mm aluminum heat sink.
- Peak torque assumes correct rms current; consult Aerotech.
- Torque constant and motor constant specified at stall.
- All performance and electrical specifications ±10%.
- Maximum winding temperature is 100°C; thermistor trips at 100°C.
- Ambient operating temperature range 0°C - 25°C. Consult Aerotech for performance in elevated ambient temperatures.
- All Aerotech amplifiers are rated A_{pk}; use torque constant in N-m/A_{pk} when sizing.

BMS Series DIMENSIONS

NEMA23



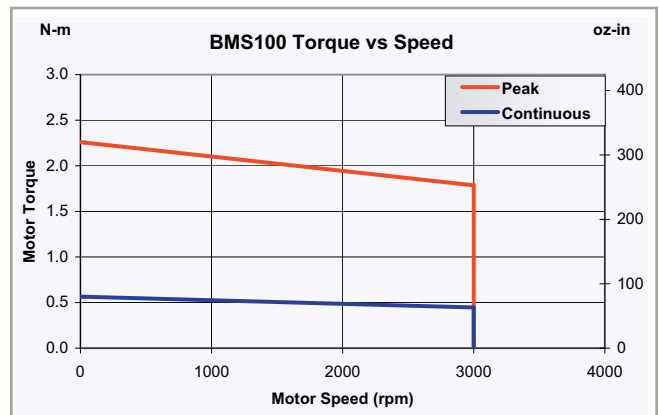
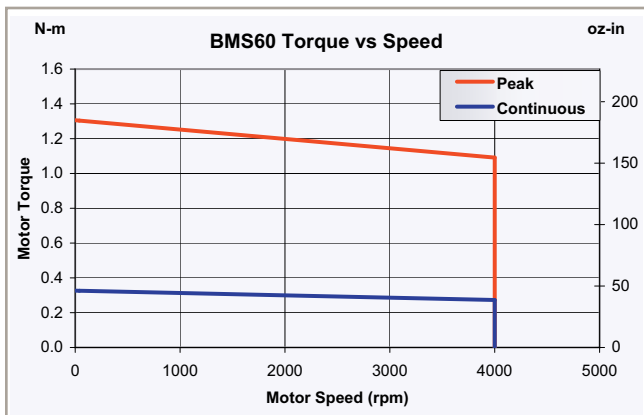
Dimensions - millimeters [inches]

| Motor Model No. | * A | * B | C |
|-----------------|------------------------|------------------------|---|
| BMS60 | $\frac{157.5}{6.20''}$ | $\frac{132.1}{5.20''}$ | $\begin{matrix} \text{Ø } 6.345 & +0.000, -0.013 \\ & 0.2498'' & +0.0000'', -0.0005'' \end{matrix}$ |
| BMS100 | $\frac{187.9}{7.40''}$ | $\frac{162.6}{6.40''}$ | $\begin{matrix} \text{Ø } 9.517 & +0.000, -0.013 \\ & 0.3747'' & +0.0000'', -0.0005'' \end{matrix}$ |

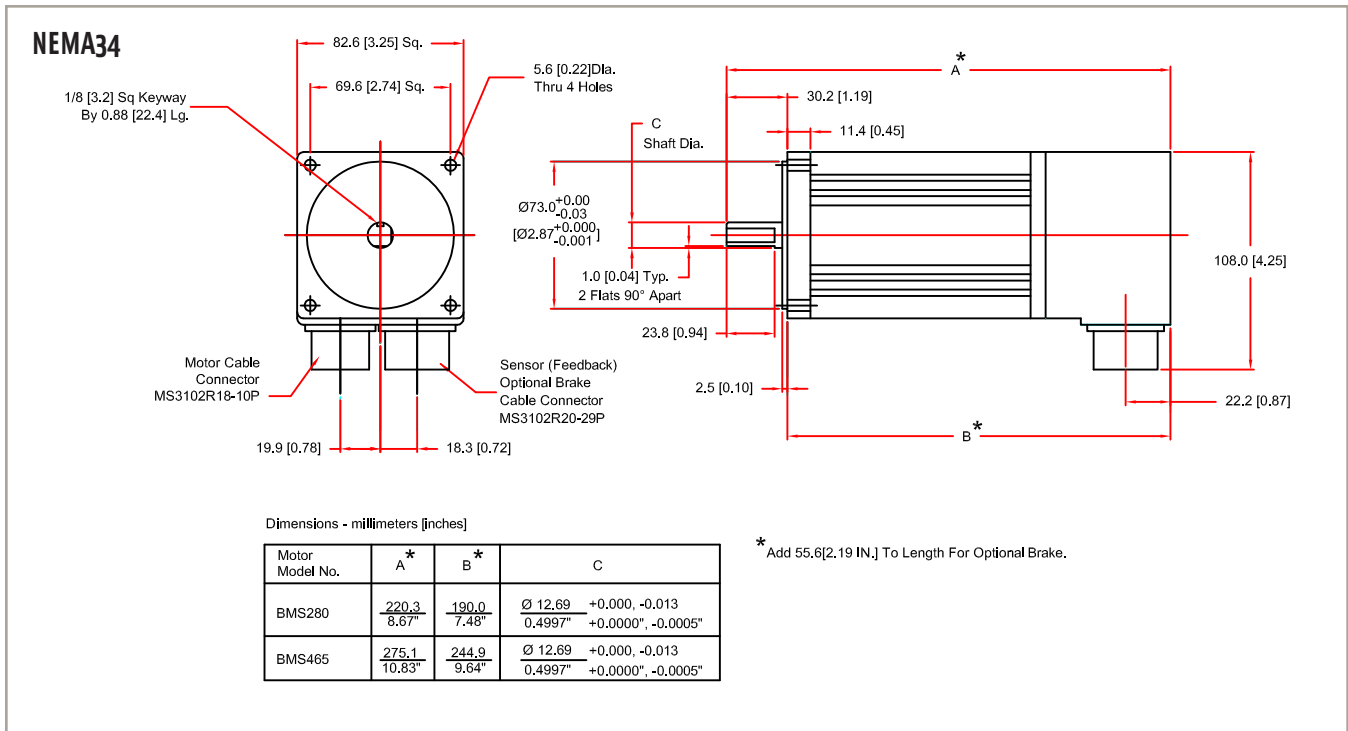
* Add 77.3 [3.04 IN.] To Length For Optional Brake.

Note: *Additional motor sizes available. Please consult factory and website for latest information

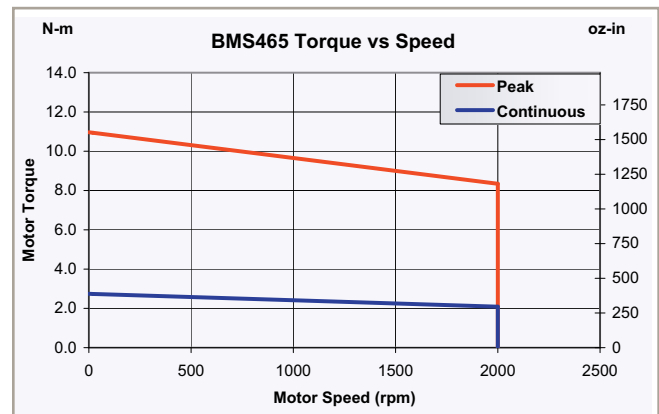
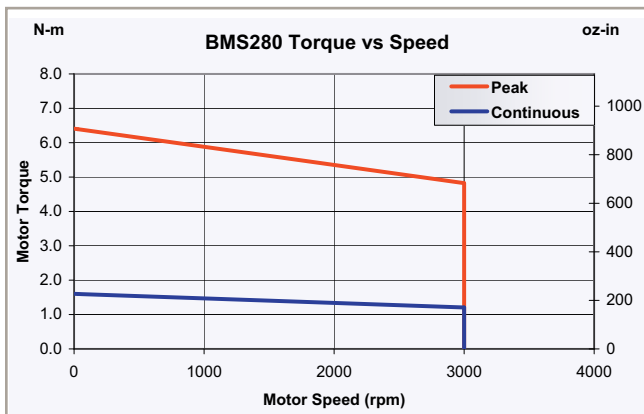
BMS Series PERFORMANCE



BMS Series DIMENSIONS



BMS Series PERFORMANCE



BMS23 Series ORDERING INFORMATION

Ordering Example

| BMS | 100 | -A | -D25 | -E1000H | -BK1 |
|--------------|---------|---------------|------------------|---|-----------|
| Motor Series | Model | Motor Winding | Connector Option | Encoder Resolution | Options |
| | 60, 100 | A, AH | D25, FLY, MS | E1000H, E2000H, E2500H, E5000H, E1000AS | BK1, VAC6 |

Brushless Rotary Servomotors

| | |
|--------|---|
| BMS60 | NEMA 23 - Tcont = 0.33 N-m (46.2 oz-in) brushless motor |
| BMS100 | NEMA 23 - Tcont = 0.56 N-m (80.0 oz-in) brushless motor |

Winding Options

| | |
|-----|---|
| -A | Standard winding |
| -AH | Standard winding with Hall board, required with AS style encoders |

Connectors

| | |
|--------|--|
| -DB25 | 25 conductor plastic D-Shell for feedback and motor power (std) |
| -MS | MS connectors for feedback and motor power |
| -FLY-x | Flying leads for feedback and motor power with custom length cable |

Feedback Options

| | |
|----------|---|
| -E1000H | 1000 line incremental squarewave encoder with marker and hall effect tracks (RS-422 line driver output) |
| -E2000H | 2000 line incremental squarewave encoder with marker and hall effect tracks (RS-422 line driver output) |
| -E2500H | 2500 line incremental squarewave encoder with marker and hall effect tracks (RS-422 line driver output) |
| -E5000H | 5000 line incremental squarewave encoder with marker and hall effect tracks (RS-422 line driver output) |
| -E1000AS | 1000 line incremental amplified sinewave encoder with marker; requires -AH winding option; maximum speed 2400 rpm |

Options

| | |
|-------|---|
| -BK1 | Brake, 112 oz-in (0.8 N-m), 24 VDC, 0.3 A for BMS60, BMS100 |
| -VAC6 | Vacuum preparation to 10 ⁻⁶ torr |

Accessories

| | |
|------------|--|
| MC-HPD25-M | Connector; HPD25 motor power mate for BMS60, BMS100 motors |
| MC-DB25-F | Connector; DB25 motor feedback mate for BMS60, BMS100 motors |
| MCM-3 | Connector; MS motor power mate for BMS60, BMS100 |
| MCF-3 | Connector; MS motor feedback mate for BMS60, BMS100 |

BMS34 Series ORDERING INFORMATION

Ordering Example

| BMS | 280 | -AH | -MS | -E2000H | -BK2 |
|--------------|----------|---------------|------------------|---|---------------|
| Motor Series | Model | Motor Winding | Connector Option | Encoder Resolution | Options |
| | 280, 465 | -AH | -MS | E1000H, E2000H, E2500H, E5000H, E1000AS | BK2, NS, VAC6 |

Brushless Rotary Servomotors

| | |
|--------|--|
| BMS280 | NEMA 34 - Tcont = 1.6 N-m (227.0 oz-in) brushless motor |
| BMS465 | NEMA 34 - Tcont = 2.86 N-m (404.8 oz-in) brushless motor |

Winding Option

| | |
|-----|---|
| -AH | Standard winding with Hall board (required for all encoder options) |
|-----|---|

Connector Option

| | |
|-----|---|
| -MS | MS connectors for feedback and motor power (standard) |
|-----|---|

Feedback Options

| | |
|----------|--|
| -E1000H | 1000 line incremental squarewave encoder with marker (RS-422 line driver output) |
| -E2000H | 2000 line incremental squarewave encoder with marker (RS-422 line driver output) |
| -E2500H | 2500 line incremental squarewave encoder with marker (RS-422 line driver output) |
| -E5000H | 5000 line incremental squarewave encoder with marker (RS-422 line driver output) |
| -E1000AS | 1000 line incremental amplified sinewave encoder with marker; maximum speed 2400 rpm |

Options

| | |
|-------|--|
| -BK2 | Brake; holding torque = 1.7 N-m (240 oz-in), 24 VDC, 0.4 A |
| -NS | IP65 rated Nitrile front shaft seal |
| -VAC6 | Vacuum preparation to 10 ⁻⁶ torr |

Example. Motor with 2000-line encoder and Nitrile shaft seal: BMS280-AH-MS-E2000H-NS

Accessories

| | |
|-------|-----------------------------------|
| MCM-3 | Connector; MS motor power mate |
| MCF-3 | Connector; MS motor feedback mate |