



WaferMaxT Hardware Manual

Revision: 1.01.00



Global Technical Support

Go to www.aerotech.com/global-technical-support for information and support about your Aerotech products. The website provides downloadable resources (such as up-to-date software, product manuals, and Help files), training schedules, and PC-to-PC remote technical support. You can also complete Product Return (RMA) forms and get information about repairs and spare or replacement parts. For immediate help, contact a service office or your sales representative. Have your customer order number available before you call or include it in your email.

United States (World Headquarters)	
Phone: +1-412-967-6440 Fax: +1-412-967-6870 Email: service@aerotech.com	101 Zeta Drive Pittsburgh, PA 15238-2811 www.aerotech.com
United Kingdom	Japan
Phone: +44 (0)1256 855055 Fax: +44 (0)1256 855649 Email: service@aerotech.co.uk	Phone: +81 (0)50 5830 6814 Fax: +81 (0)43 306 3773 Email: service@aerotechkk.co.jp
Germany	China
Phone: +49 (0)911 967 9370 Fax: +49 (0)911 967 93720 Email: service@aerotechgmbh.de	Phone: +86 (21) 3319 7715 Email: service@aerotech.com
France	Taiwan
Phone: +33 2 37 21 87 65 Email: service@aerotech.co.uk	Phone: +886 (0)2 8751 6690 Email: service@aerotech.tw

This manual contains proprietary information and may not be reproduced, disclosed, or used in whole or in part without the express written permission of Aerotech, Inc. Product names mentioned herein are used for identification purposes only and may be trademarks of their respective companies.

Copyright © 2016-2017, Aerotech, Inc., All rights reserved.

Aerotech Worldwide

United States ■ France ■ Germany ■ United Kingdom
China ■ Japan ■ Taiwan



Table of Contents

- WaferMaxT Hardware Manual** **1**
 - Table of Contents 3
 - List of Figures 4
 - List of Tables 5
 - EC Declaration of Incorporation 6
 - Safety Procedures and Warnings 7

- Chapter 1: Overview** **9**
 - 1.1. Environmental Specifications 10
 - 1.2. Accuracy and Temperature Effects 10
 - 1.3. Basic Specifications 11

- Chapter 2: Installation** **13**
 - 2.1. Unpacking and Handling the Stage 13
 - 2.2. Dimensions 14
 - 2.3. Securing the Stage to the Mounting Surface 15
 - 2.4. Attaching the Payload to the Stage 17

- Chapter 3: Electrical Installation** **19**
 - 3.1. Motor and Feedback Connectors 20
 - 3.2. Motor and Feedback Wiring 23
 - 3.3. Motor and Feedback Specifications 24
 - 3.4. Machine Direction 26
 - 3.5. Motor and Feedback Phasing 27

- Chapter 4: Maintenance** **29**
 - 4.1. Service and Inspection Schedule 29
 - 4.2. Cleaning and Lubrication 30
 - 4.3. Troubleshooting 31

- Appendix A: Warranty and Field Service** **33**

- Appendix B: Revision History** **35**

- Index** **37**

List of Figures

Figure 2-1: WaferMaxT Dimensions 14
Figure 2-2: Mounting Hole Locations 16
Figure 2-3: Stage Orientations 17
Figure 2-4: Cantilevered Load Capability 18
Figure 3-1: Motor and Feedback Wiring 23
Figure 3-2: Machine Direction 26
Figure 3-3: Hall Phasing 27
Figure 3-4: Analog Encoder Phasing Reference Diagram 28

List of Tables

Table 1-1: Model Numbering System	9
Table 1-2: Environmental Specifications	10
Table 1-3: WaferMaxT Series Specifications	11
Table 2-1: Stage to Mounting Surface Hardware	16
Table 3-1: Motor Pin Assignments	21
Table 3-2: Feedback Pin Assignments	22
Table 3-3: Feedback Specifications	24
Table 3-4: WaferMaxT Motor Specifications (S-180-44-A Slotless Motor)	25
Table 3-5: Encoder Specifications	25

EC Declaration of Incorporation

Manufacturer: Aerotech, Inc.
101 Zeta Drive
Pittsburgh, PA 15238-2811
USA

herewith declares that the product:
WaferMaxT Rotary Stage

is intended to be incorporated into machinery to constitute machinery covered by the Directive 2006/42/EC as amended;

and that the following harmonized European standards have been applied:

EN ISO 12100:2010

Safety of machinery - Basic concepts, general principles for design

EN 60204-1:2010

Safety of machinery - Electrical equipment of machines - Part 1: General requirements

and further more declares that

it is not allowed to put the equipment into service until the machinery into which it is to be incorporated or of which it is to be a component has been found and declared to be in conformity with the provisions of the Directive 2006/42/EC and with national implementing legislation, i.e., as a whole, including the equipment referred to in this Declaration.

This is to certify that the aforementioned product is in accordance with the applicable requirements of the following Directive(s):

2011/65/EU

RoHS 2 Directive

Authorized Representative: Simon Smith, European Director
Address: Aerotech Ltd
The Old Brick Kiln
Ramsdell, Tadley
Hampshire RG26 5PR
UK

Name  / Alex Weibel
Position Engineer Verifying Compliance
Location Pittsburgh, PA

Safety Procedures and Warnings

Read this manual in its entirety before installing, operating, or servicing this product. If you do not understand the information contained herein, contact an Aerotech representative before proceeding. Strictly adhere to the statements given in this section and other handling, use, and operational information given throughout the manual to avoid injury to you and damage to the equipment.

The following statements apply wherever the Warning or Danger symbol appears within this manual. Failure to observe these precautions could result in serious injury to those individuals performing the procedures and/or damage to the equipment.



DANGER: This product contains potentially lethal voltages. To reduce the possibility of electrical shock, bodily injury, or death the following precautions must be followed.

1. Access to the WaferMaxT and component parts must be restricted while connected to a power source.
2. Do not connect or disconnect any electrical components or connecting cables while connected to a power source.
3. Disconnect electrical power before servicing equipment.
4. All components must be properly grounded in accordance with local electrical safety requirements.
5. Operator safeguarding requirements must be addressed during final integration of the product.



WARNING: To minimize the possibility of electrical shock, bodily injury or death the following precautions must be followed.

1. Moving parts can cause crushing or shearing injuries. Access to all stage and motor parts must be restricted while connected to a power source.
2. Cables can pose a tripping hazard. Securely mount and position all system cables to avoid potential hazards.
3. Do not expose this product to environments or conditions outside of the listed specifications. Exceeding environmental or operating specifications can cause damage to the equipment.
4. The WaferMaxT must be mounted securely. Improper mounting can result in injury and damage to the equipment.
5. Use care when moving the WaferMaxT . Lifting or transporting the WaferMaxT improperly can result in injury or damage to the WaferMaxT.
6. This product is intended for light industrial manufacturing or laboratory use. Use of this product for unintended applications can result in injury and damage to the equipment.
7. If the product is used in a manner not specified by the manufacturer, the protection provided by the product can be impaired and result in damage, shock, injury, or death.
8. Operators must be trained before operating this equipment.
9. All service and maintenance must be performed by qualified personnel.
10. Eye protection must be worn when in the proximity of compressed air components.

This page intentionally left blank.

Chapter 1: Overview

NOTE: Aerotech continually improves its product offerings; listed options may be superseded at any time. All drawings and illustrations are for reference only and were complete and accurate as of this manual's release. Refer to www.aerotech.com for the most up-to-date information.

Table 1-1: Model Numbering System

Model	
WaferMaxT	Direct-drive rotary stage with 25 mm clear aperture
Feedback	
-E1	Incremental Encoder; 2048 lines/rev; 1 Vpp output
-E2	Incremental Encoder; 10000 lines/rev; 1 Vpp output
Rotary Union	
	None
-RU1	Rotary union for feed-through of air/vacuum, single port
Integration	
-TAC	Test as Component
-TAS	Test as System

1.1. Environmental Specifications



WARNING: Do not expose this product to environments or conditions outside of the listed specifications. Exceeding environmental or operating specifications can cause damage to the equipment.

Table 1-2: Environmental Specifications

Ambient Temperature	Operating: 10° to 35° C (50° to 95° F) The optimal operating temperature is 20° C ±2° C (68° F ±4° F). If at any time the operating temperature deviates from 20° C degradation in performance could occur.
	Storage: 0° to 40° C (32° to 104° F) in original shipping packaging
Humidity	Operating: 20% to 60% RH
	Storage: 10% to 70% RH, non-condensing in original packaging. The stage should be packaged with desiccant if it is to be stored for an extended time.
Altitude	Operating: 0 m to 2,000 m (0 ft to 6,562 ft) above sea level Contact Aerotech if your specific application involves use above 2,000 m or below sea level.
Vibration	Use the system in a low vibration environment. Excessive floor or acoustical vibration can affect system performance. Contact Aerotech for information regarding your specific application.
Protection Rating	The WaferMaxT is not suitable for dusty or wet environments. This equates to an ingress protection rating of IP00.
Use	Indoor use only

1.2. Accuracy and Temperature Effects

Aerotech products are designed for and built in a 20°C (68°F) environment. Extreme temperature changes could cause a decrease in performance or permanent damage to the WaferMaxT. At a minimum, the environmental temperature must be controlled to within 0.25°C per 24 hours to ensure the WaferMaxT specifications are repeatable over an extended period of time. The severity of temperature effects on all specifications depends on many different environmental conditions, including how the WaferMaxT is mounted. Contact the factory for more details.

1.3. Basic Specifications

NOTE: Aerotech continually improves its product offerings; listed options may be superseded at any time. All drawings and illustrations are for reference only and were complete and accurate as of this manual's release. Refer to www.aerotech.com for the most up-to-date information.

Table 1-3: WaferMaxT Series Specifications

		WaferMaxT
Travel		360 degrees, continuous
Tabletop Diameter		106.7 mm
Drive System		Direct-Drive Brushless Servomotor
Maximum Bus Voltage		up to 340 VDC
Maximum Torque (Continuous)		5.99 N·m
Encoder		2048 lines/rev fundamental; 10000 lines/rev fundamental
Accuracy ⁽¹⁾		±25 µrad (±5 arc sec)
Bidirectional Repeatability ⁽³⁾		±10 µrad (±2 arc sec)
Tilt Error Motion		97 µrad (20 arc sec)
Axial Error Motion		5 µm
Radial Error Motion		5 µm
Maximum Speed		400 rpm (unloaded)
Maximum Load ⁽²⁾	Axial	40 kg
	Radial	20 kg
Inertia		0.008130 kg·m ²
Mass		7.0 kg
Material		Aluminum
Finish		Black Anodize
1. Available with Aerotech controllers 2. Maximum loads are mutually exclusive. 3. Specifications are per axis measured 25 mm above the tabletop without a payload. Performance is payload and work-point dependent. Consult factory for multi-axis or non-standard applications.		

This page intentionally left blank.

Chapter 2: Installation



WARNING: WaferMaxT installation must be in accordance to instructions provided by this manual and any accompanying documentation. Failure to follow these instructions could result in injury or damage to the equipment.

2.1. Unpacking and Handling the Stage



WARNING: It is the customer's responsibility to safely and carefully lift and move the WaferMaxT.

- Secure all moving parts before lifting or moving the WaferMaxT to a new location. Unsecured moving parts could shift and cause bodily injury.
- Improper handling could adversely affect the WaferMaxT's performance. Use care when lifting or moving the WaferMaxT.

Carefully remove the WaferMaxT from its protective shipping container. Gently set the WaferMaxT on a smooth, flat, and clean surface.

Before operating the WaferMaxT, it is important to let it stabilize at room temperature for at least 12 hours. Allowing it to stabilize to room temperature will ensure that all of the alignments, preloads, and tolerances are the same as they were when tested at Aerotech. Use compressed nitrogen or clean, dry, oil-less air to remove any dust or debris that has collected during shipping.

Each WaferMaxT has a label listing the system part number and serial number. These numbers contain information necessary for maintaining or updating system hardware and software. Locate this label and record the information for later reference.

If the WaferMaxT has shipped as part of a system, shipping clamps (typically red, anodized aluminum) may have been installed to secure the system prior to shipment. The shipping clamps, if installed, will need to be removed prior to machine start up.

2.2. Dimensions

NOTE: Aerotech continually improves its product offerings; listed options may be superseded at any time. All drawings and illustrations are for reference only and were complete and accurate as of this manual's release. Refer to www.aerotech.com for the most up-to-date information.

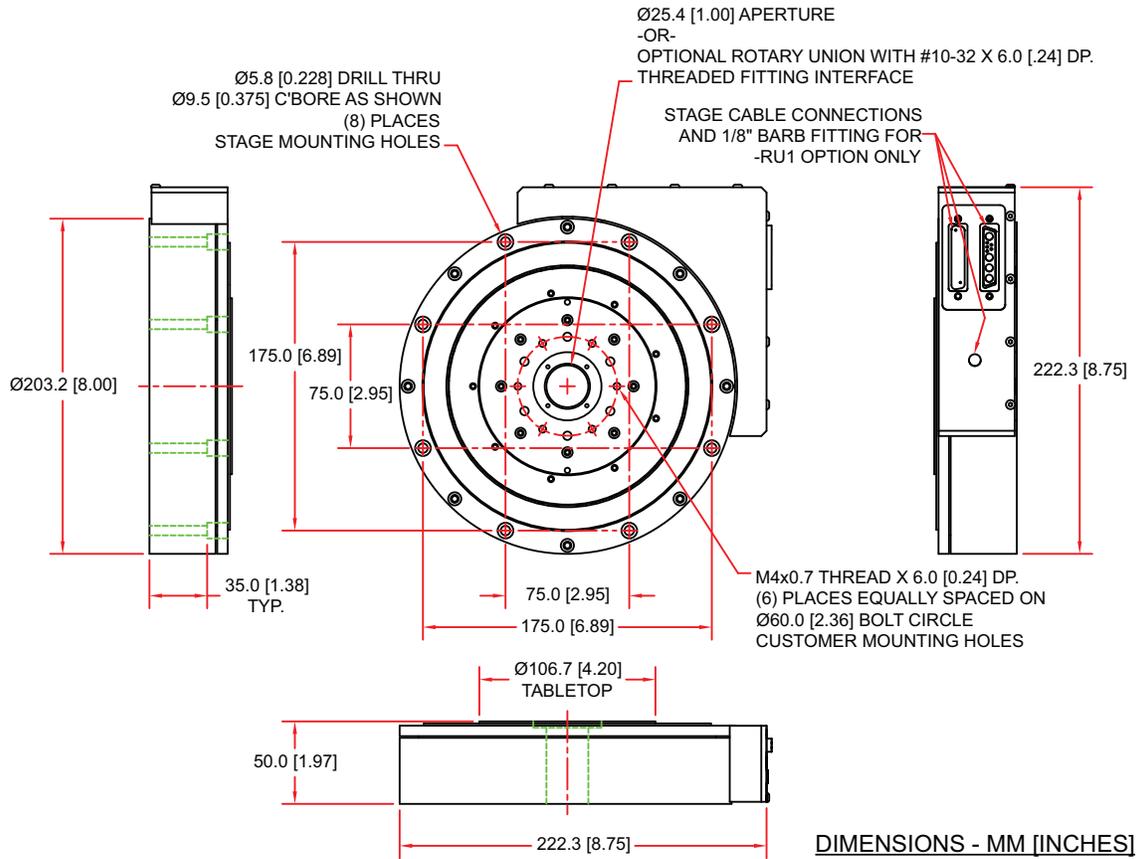


Figure 2-1: WaferMaxT Dimensions

2.3. Securing the Stage to the Mounting Surface



WARNING: The WaferMaxT must be mounted securely. Improper mounting can result in injury and damage to the equipment.



WARNING: Make sure that all moving parts are secure before moving the WaferMaxT. Unsecured moving parts may shift and cause bodily injury.

The mounting surface must be flat and have adequate stiffness in order to achieve the maximum performance from the WaferMaxT stage. When it is mounted to a non-flat surface, the stage can be distorted as the mounting screws are tightened. This distortion will decrease overall accuracy. Adjustments to the mounting surface must be done before the stage is secured.

Inspect the mounting surface for dirt or unwanted residue and clean if necessary. Use precision flatstones on the mounting surface to remove any burrs or high spots. Clean the mounting surface with a lint free cloth and acetone or isopropyl alcohol and allow the cleaning solvent to completely dry. Gently place the stage on the mounting surface.

NOTE: To maintain accuracy, the mounting surface must be flat to within 5 μm .

NOTE: The WaferMaxT is precision machined and verified for flatness prior to product assembly at the factory. If machining is required to achieve the desired flatness, it should be performed on the mounting surface rather than the WaferMaxT. Shimming should be avoided if possible. If shimming is required, it should be minimized to retain maximum rigidity of the system.

This stage is designed to use socket head cap screws (SHCS) to secure the base to the mounting surface (refer to [Figure 2-2](#)).

Tightening torque values for the mounting hardware are dependent on the properties of the surface to which the stage is being mounted. Values provided in [Table 2-1](#) are typical values and may not be accurate for your mounting surface. Refer to [Section 2.2](#) for specific model mounting locations and dimensions.

Table 2-1: Stage to Mounting Surface Hardware

Mounting Hardware	Typical Screw Torque
M5 SHCS	4 N·m

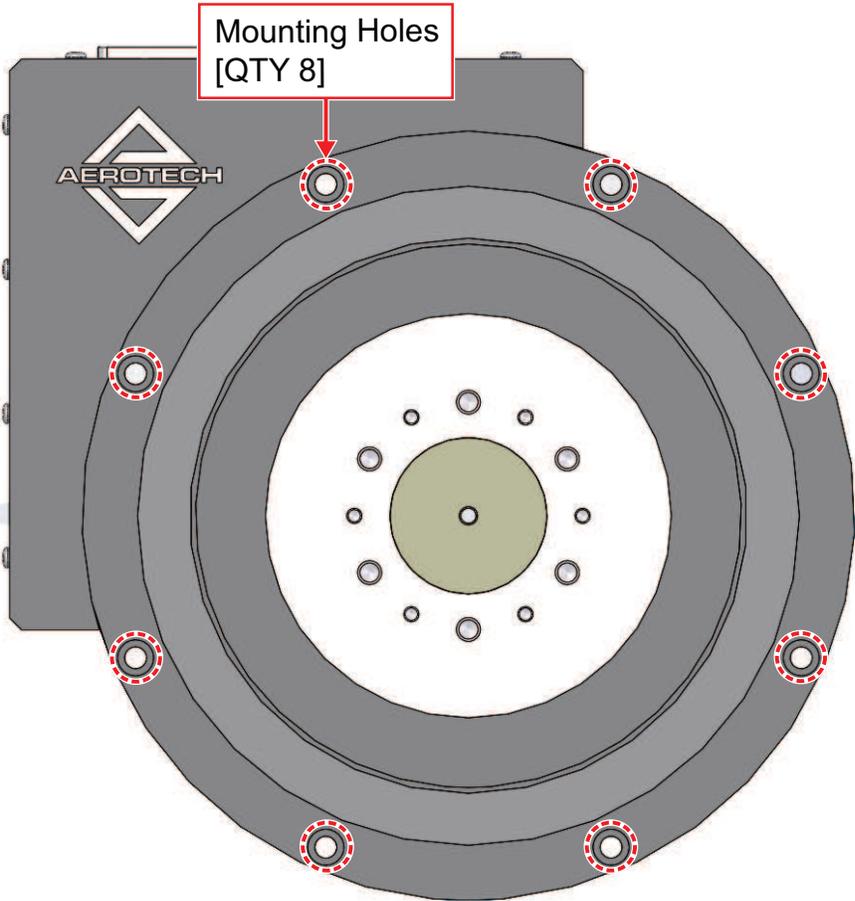


Figure 2-2: Mounting Hole Locations

2.4. Attaching the Payload to the Stage

Inspect the mounting surface for dirt or unwanted residue and clean if necessary. Clean the mounting surface with a lint free cloth and acetone or isopropyl alcohol and allow the cleaning solvent to completely dry.

To prevent damage to the payload or stage, test the operation of the stage before the payload is attached. Aerotech recommends that customers use a representative payload during start-up to prevent accidental damage to the stage and the payload. Proceed with the electrical installation and test the motion control system in accordance with the system documentation. Document all results for future reference. For information on electrical installation refer to [Chapter 3](#) and the documentation delivered with the stage.

NOTE: If your WaferMaxT was purchased with Aerotech controls, it might have been tuned with a representative payload based on the information provided at the time of order. If the WaferMaxT is started up without a payload, the servo gains provided by Aerotech with the shipment may not be appropriate and servo instability can occur. Refer to the controller help file for tuning assistance.

The payload must be flat, rigid, and comparable to the stage in quality to maintain optimum performance.

NOTE: For valid system performance, the mounting interface should be flat within 13 μm .



WARNING: Refer to the dimensions in [Section 2.2](#) for maximum allowable thread engagement. A screw extending through the stage table can affect travel and damage the stage.

Applied loads should be symmetrically distributed whenever possible (i.e., the payload should be centered on the stage table and the entire stage should be centered on the support structure).

If cantilevered loads are applied, refer to [Figure 2-3](#) to find the loading condition. Refer to [Figure 2-4](#) to find the maximum allowable load.

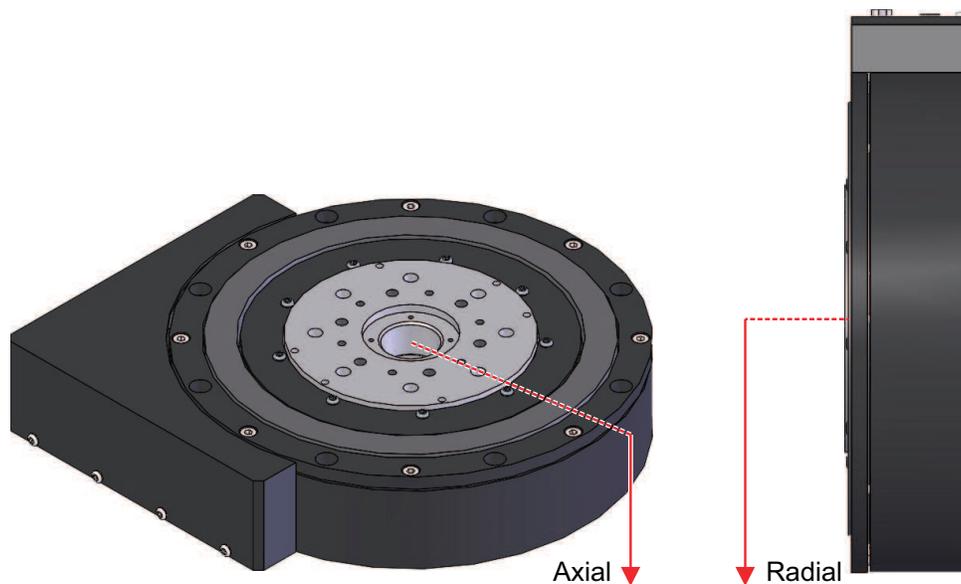


Figure 2-3: Stage Orientations

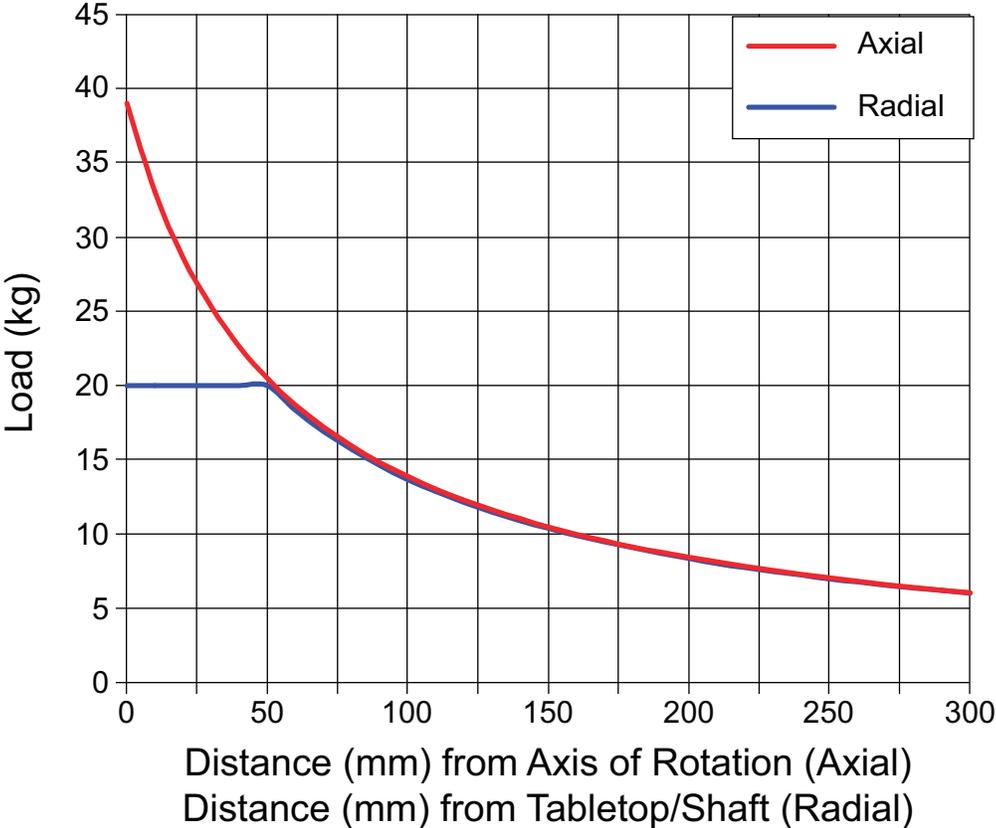


Figure 2-4: Cantilevered Load Capability

Chapter 3: Electrical Installation



WARNING: Electrical installation must be performed by properly qualified personnel.

Electrical installation requirements will vary depending on product options. Installation instructions in this section are for WaferMaxTs equipped with standard Aerotech motors intended for use with an Aerotech motion control system. Contact Aerotech for further information regarding products that are otherwise configured.

Aerotech motion control systems are adjusted at the factory for optimum performance. When the WaferMaxT is part of a complete Aerotech motion control system, setup usually involves connecting the WaferMaxT to the appropriate drive chassis with the cables provided. Labels on the system components usually indicate the appropriate connections.

If system level integration was purchased, an electrical drawing showing system interconnects has been supplied with the system (separate from this documentation).

The electrical wiring from the motor and encoder are integrated at the factory. Refer to the following sections for standard motor wiring and connector pin assignments.



WARNING: Applications requiring access to the stage while it is energized will require additional grounding and safeguards. The System Integrator or qualified installer is responsible for determining and meeting all safety and compliance requirements necessary for the integration of this stage into the final application.



DANGER: Remove power before connecting or disconnecting electrical components or cables. Failure to do so may cause electric shock.



WARNING: Operator access to the base and tabletop must be restricted while connected to a power source. Failure to do so may cause electric shock.

3.1. Motor and Feedback Connectors

Stages equipped with standard motors and encoders come from the factory completely wired and assembled.

NOTE: Refer to the other documentation accompanying your Aerotech equipment. Call your Aerotech representative if there are any questions on system configuration.

NOTE: If using standard Aerotech motors and cables, motor and encoder connection adjustments are not required.

The WaferMaxT's protective ground connection provides motor frame ground protection only. Additional grounding and safety safeguards are required for applications requiring access to the stage while it is energized. The System Integrator or qualified installer is responsible for determining and meeting all safety and compliance requirements necessary for the integration of this stage into the final application.



DANGER: Remove power before connecting or disconnecting electrical components or cables. Failure to do so may cause electric shock.



WARNING: The protective ground connection must be properly installed to minimize the possibility of electric shock.



WARNING: Operator access to the base and tabletop must be restricted while connected to a power source. Failure to do so may cause electric shock.



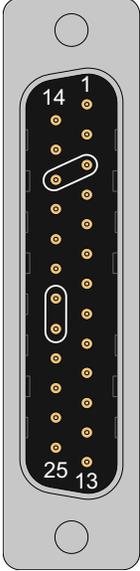
CAUTION: The stage controller must provide over-current and over-speed protection. Failure to do so may result in permanent damage to the motor and stage components.

Table 3-1: Motor Pin Assignments

Pin	Description	Connector
A1	Motor Phase A	
A2	Motor Phase B	
A3	Motor Phase C	
1	Motor Shield (EMI shield)	
2	Reserved	
3	Reserved	
4	Reserved	
5	Reserved	
A4	Frame ground (motor protective ground)	

Mating Connector	Aerotech P/N	Third Party P/N
Backshell	ECK00656	Amphenol #17E-1726-2
Sockets [QTY. 4]	ECK00659	ITT Cannon #DM53744-6
Connector	ECK00657	ITT Cannon #DBMM9W4SA197

Table 3-2: Feedback Pin Assignments

Pin	Description	Connector
1	Signal shield connection	
2	Over-Temperature Thermistor sensor	
3	+5 V power supply (internally connected to Pin 16)	
4	Reserved	
5	Hall Effect sensor, phase B	
6	Marker-N	
7	Marker	
8	Reserved	
9	Reserved	
10	Hall Effect sensor, phase A	
11	Hall Effect sensor, phase C	
12	Reserved	
13	Reserved	
14	Cosine	
15	Cosine-N	
16	+5 V power supply (internally connected to Pin 3)	
17	Sine	
18	Sine-N	
19	Reserved	
20	Common ground (internally connected to Pin 21)	
21	Common ground (internally connected to Pin 20)	
22	Reserved	
23	Fault output from encoder	
24	Reserved	
25	Reserved	
Case	Signal shield connection (to case)	

Mating Connector	Aerotech P/N	Third Party P/N
Backshell	ECK00656	Amphenol #17E-1726-2
Connector	ECK00300	FCI DB25S064TLF

3.2. Motor and Feedback Wiring

Shielded cables are required for the motor and feedback connections.

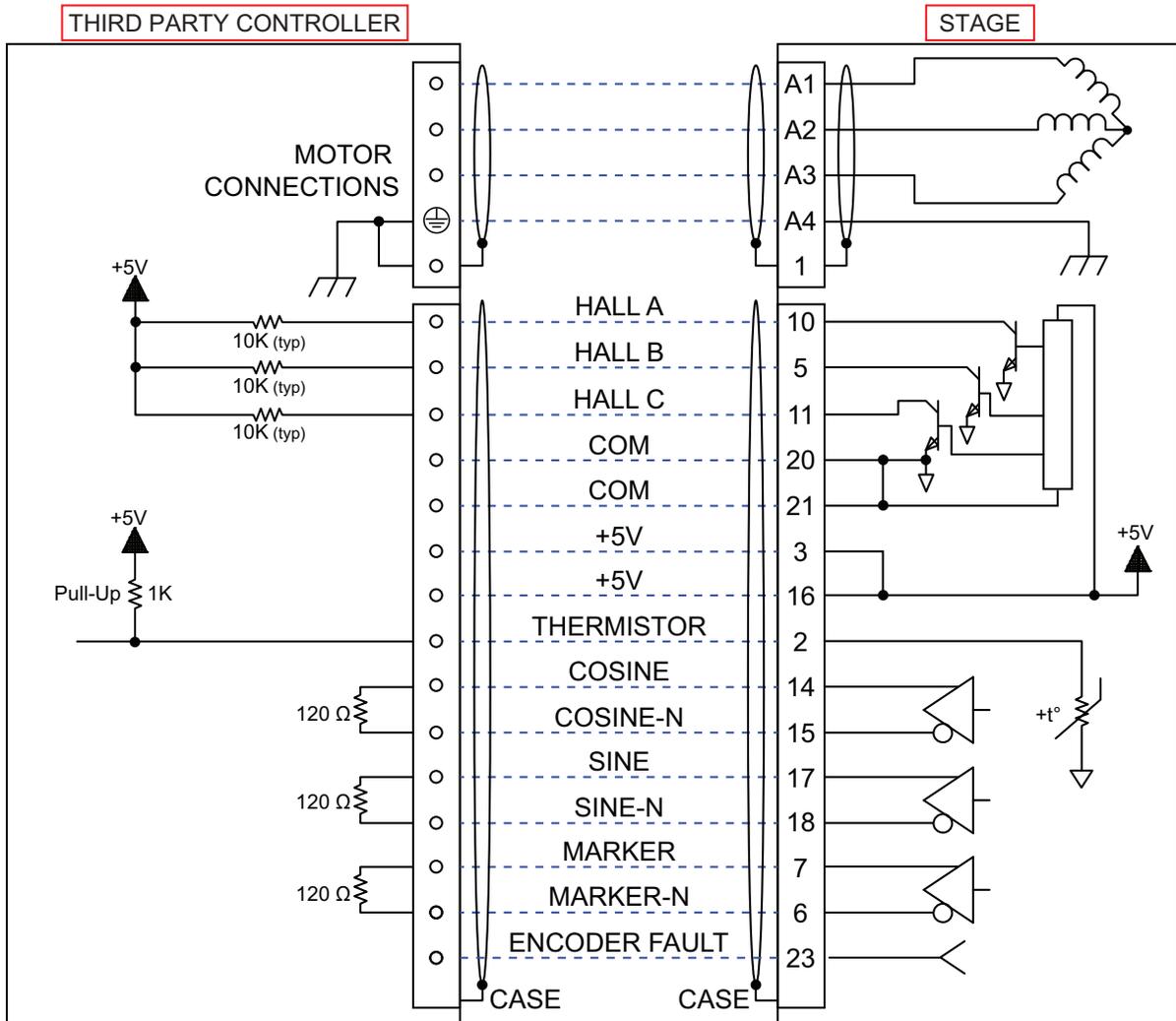


Figure 3-1: Motor and Feedback Wiring

3.3. Motor and Feedback Specifications

Table 3-3: Feedback Specifications

Hall-Effect Sensors Specifications	
Supply Voltage	5 V
Supply Current	50 mA
Output Type	Open Collector
Output Voltage	24 V max (pull up)
Output Current	5 mA (sinking)

Thermistor Specifications	
Polarity	Logic "0" (no fault)
	Logic "1" (over-temperature fault)
Cold Resistance	100 Ω
Hot Resistance	10 K
Note: 1K pull-up to +5V recommended.	

Encoder Specifications	
Supply Voltage	5 V \pm 10%
Supply Current	250 mA
Output Signals	Sinusoidal Type (Incremental Encoder): 1 V _{pk-pk} into 120 Ω Load (differential signals SIN+, SIN-, COS+, COS- are .5 V _{pk-pk} relative to ground.)

NOTE: Aerotech continually improves its product offerings; listed options may be superseded at any time. All drawings and illustrations are for reference only and were complete and accurate as of this manual's release. Refer to www.aerotech.com for the most up-to-date information.

Table 3-4: WaferMaxT Motor Specifications (S-180-44-A Slotless Motor)

		S-180-44
Performance Specifications (1,5)		
Winding Designation		A
Stall Torque, Cont. (2)	N·m	5.99
Peak Torque (3)	N·m	23.98
Electrical Specifications (5)		
Winding Designation		A
BEMF Const., line-line, Max	$V_{pk}/krpm$	268.7
Continuous Current, Stall (2)	A_{pk}	2.7
	A_{rms}	1.9
Peak Current, Stall (2)	A_{pk}	10.8
	A_{rms}	7.6
Torque Constant (4, 9)	$N·m/A_{pk}$	2.22
	$N·m/A_{rms}$	3.14
Motor Constant (2, 4)	$N·m/\sqrt{W}$	0.628
Resistance, 25°C, line-line	Ω	12.8
Inductance, line-line	mH	3.40
Maximum Bus Voltage	V_{DC}	340
Thermal Resistance	°C/W	0.82
Number of Poles	--	18
1. Performance is dependent upon heat sink configuration, system cooling conditions, and ambient temperature 2. Values shown @ 75°C rise above a 25 °C ambient temperature, with housed motor mounted to a 330 mm x 330 mm x 13 mm aluminum heat sink 3. Peak force assumes correct rms current; consult Aerotech. 4. Torque constant and motor constant specified at stall 5. All performance and electrical specifications ±10% 6. Specifications given are for the motor only. When integrated into a housing with bearings additional losses should be considered. 7. Maximum winding temperature is 100 °C (thermistor trips at 100 °C) 8. Ambient operating temperature range 0°C - 25°C; consult Aerotech for performance in elevated ambient temperatures 9. All Aerotech amplifiers are rated A_{pk} ; use torque constant in $N·m/A_{pk}$ when sizing		

Table 3-5: Encoder Specifications

Feedback	Fundamental Signal Period	Digital Resolution ²
-E1	2048 lines/rev	0.16/0.04 arc sec/line
-E2	10000 lines/rev	0.0324/0.0081 arc sec/line
1. Quadrature decoding included in interpolated resolution calculations 2. -AS shows x4000/x16000 total interpolation		

3.4. Machine Direction

Aerotech stages are configured to have positive and negative "machine" directions. The machine direction defines the phasing of the feedback and motor signals and is dictated by the stage wiring (refer to [Section 3.5](#) for Motor and Feedback phasing information). Programming direction of a stage is set by the controller that is used to move the stage. Programming direction is typically selectable in the controller, while machine direction is hardwired in the stage. [Figure 3-2](#) shows the machine direction of WaferMaxT stages.

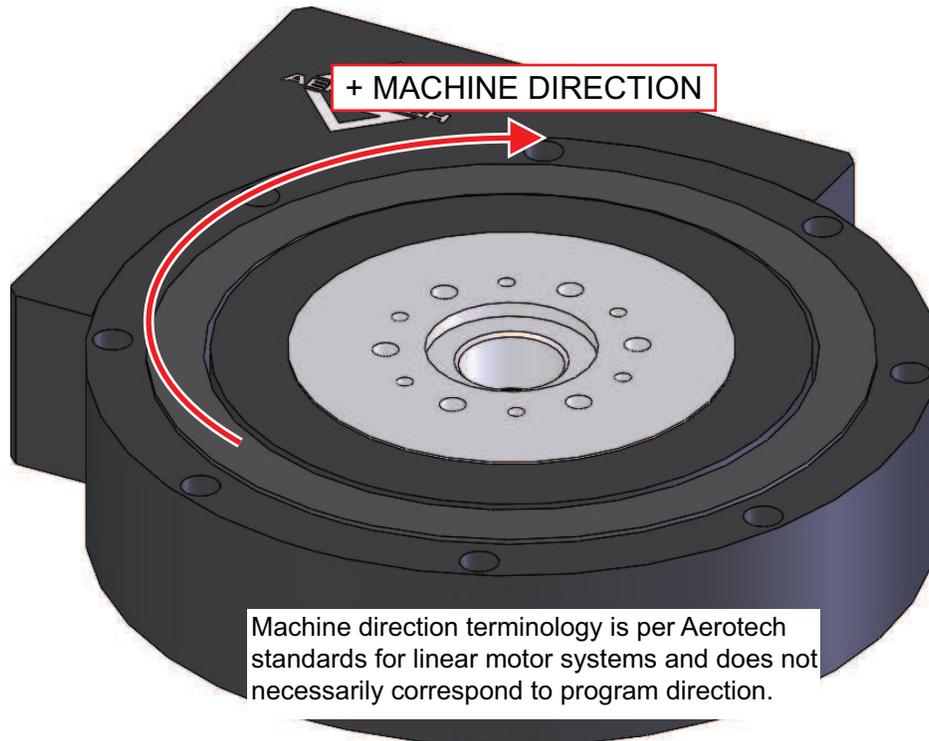
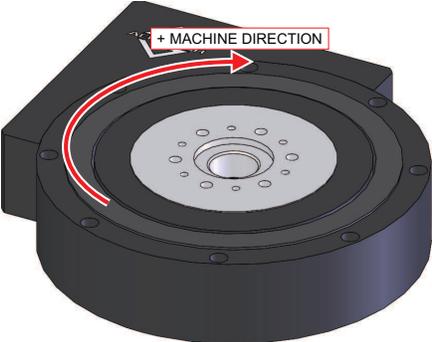
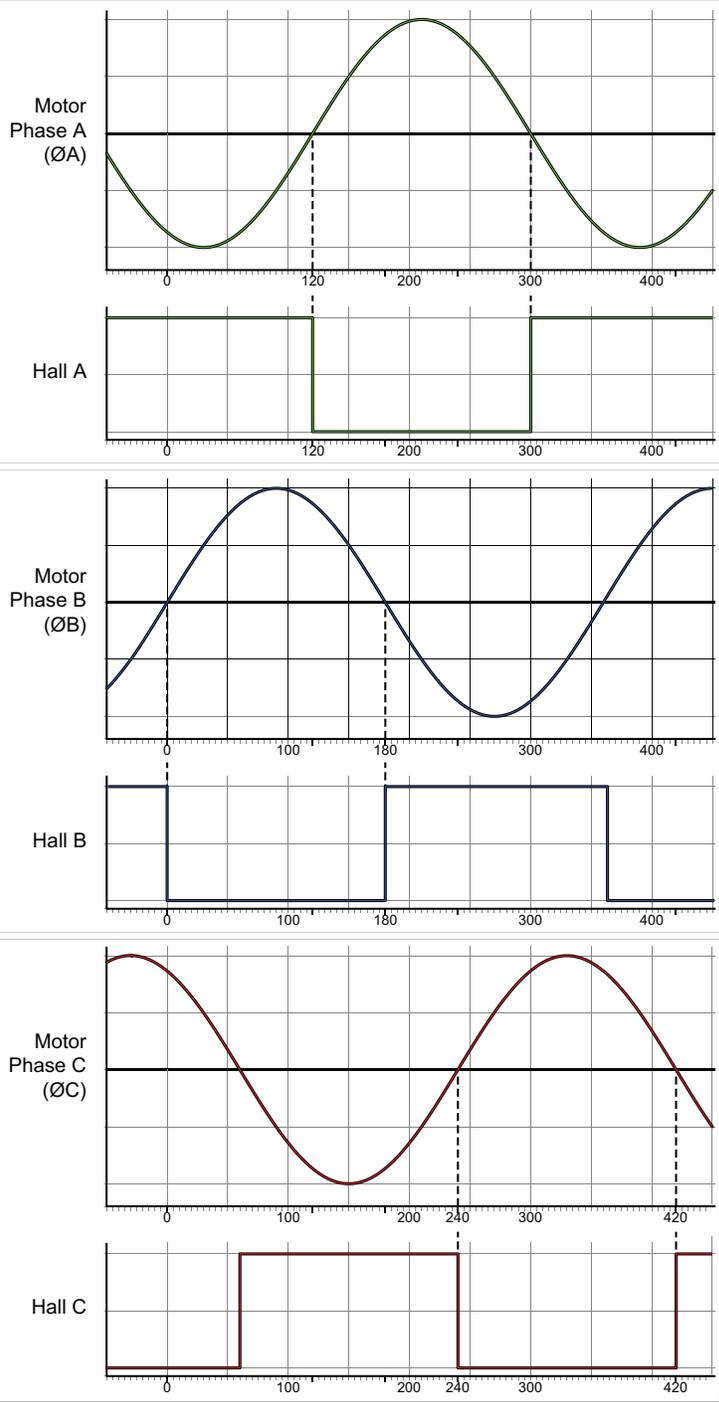


Figure 3-2: Machine Direction

3.5. Motor and Feedback Phasing

Motor phase voltage is measured relative to the virtual wye common point.



Positive MOVE (Clockwise) →

Figure 3-3: Hall Phasing

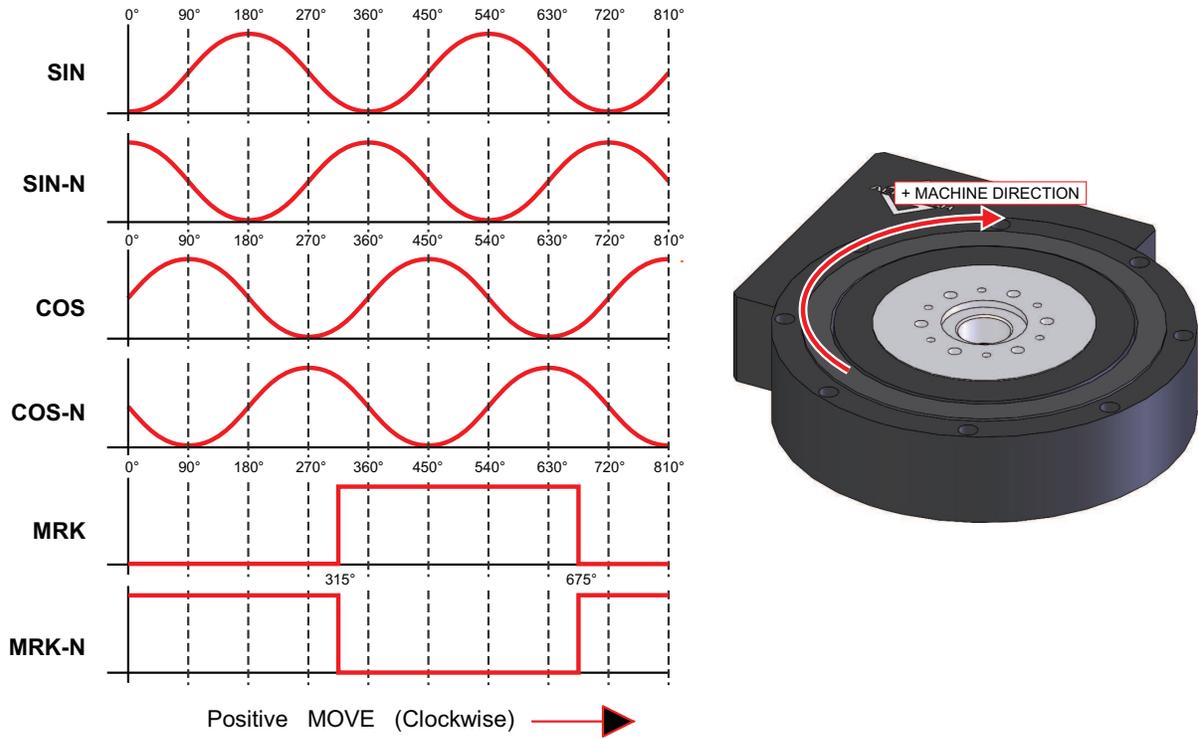


Figure 3-4: Analog Encoder Phasing Reference Diagram

Chapter 4: Maintenance



DANGER: To minimize the possibility of bodily injury or death, disconnect all electrical power prior to performing any maintenance or making adjustments to the equipment.

4.1. Service and Inspection Schedule

Inspect the WaferMaxT once per month. A longer or shorter inspection interval may be required depending on the specific application, and conditions such as the duty cycle, speed, and environment.

In general, stages operating in a clean environment should be cleaned annually. For stages operating under conditions involving excessive debris, stages should be cleaned every six months. In normal operating conditions and with proper cleanliness of the stage, the bearing will not require lubrication or maintenance for the life of the stage.

If the application process uses only a small portion of travel for most of the duty cycle, periodically drive the stage through full travel to redistribute the lubrication in the bearings. The motor is completely non-contact and requires no lubrication.

Monthly inspections should include but not be limited to:

- Visually inspect the stage and cables
- Re-tighten loose connectors
- Replace or repair damaged cables
- Clean the WaferMaxT and any components and cables as needed
- Repair any damage before operating the WaferMaxT
- Inspect and perform an operational check on all safeguards and protective devices

4.2. Cleaning and Lubrication



DANGER: To minimize the possibility of bodily injury or death, disconnect all electrical power prior to performing any maintenance or making adjustments to the equipment.



WARNING: Further disassembly of the stage is not recommended because proper assembly and calibration can only be done at the factory. In addition, a laser interferometer is required for post assembly verification to maintain warranties. Contact Aerotech for more information.

The bearings, motors, and encoders for the WaferMaxT series require no added lubrication or maintenance. Periodic cleaning is recommended.

Recommended Cleaning Solvents

Before using a cleaning solvent on any part of the WaferMaxT, blow away small particles and dust with nitrogen or, less preferably, clean, dry, compressed air.

Any external metal surface of the WaferMaxT can be cleaned with isopropyl alcohol on a lint-free cloth.

4.3. Troubleshooting

Symptom	Possible Cause and Solution
Stage will not move	<ul style="list-style-type: none">• In Limit condition. Check limits (refer to Chapter 3) and refer to controller documentation for polarity and compatibility requirements (Example: voltage requirements).• Controller trap or fault (refer to controller documentation).• Stage cables not connected (or incorrectly connected) to controller (refer to system documentation).
Stage moves uncontrollably	<ul style="list-style-type: none">• Encoder (sine and cosine) signal connections (refer to Chapter 3 and Controller documentation).• Motor Connections (refer to Chapter 3 and Controller documentation).
Stage oscillates or squeals	<ul style="list-style-type: none">• Gains misadjusted (refer to the controller documentation).• Encoder signals (refer to the controller documentation).

This page intentionally left blank.

Appendix A: Warranty and Field Service

Aerotech, Inc. warrants its products to be free from harmful defects caused by faulty materials or poor workmanship for a minimum period of one year from date of shipment from Aerotech. Aerotech's liability is limited to replacing, repairing or issuing credit, at its option, for any products that are returned by the original purchaser during the warranty period. Aerotech makes no warranty that its products are fit for the use or purpose to which they may be put by the buyer, whether or not such use or purpose has been disclosed to Aerotech in specifications or drawings previously or subsequently provided, or whether or not Aerotech's products are specifically designed and/or manufactured for buyer's use or purpose. Aerotech's liability on any claim for loss or damage arising out of the sale, resale, or use of any of its products shall in no event exceed the selling price of the unit.

THE EXPRESS WARRANTY SET FORTH HEREIN IS IN LIEU OF AND EXCLUDES ALL OTHER WARRANTIES, EXPRESSED OR IMPLIED, BY OPERATION OF LAW OR OTHERWISE. IN NO EVENT SHALL AEROTECH BE LIABLE FOR CONSEQUENTIAL OR SPECIAL DAMAGES.

Return Products Procedure

Claims for shipment damage (evident or concealed) must be filed with the carrier by the buyer. Aerotech must be notified within thirty (30) days of shipment of incorrect material. No product may be returned, whether in warranty or out of warranty, without first obtaining approval from Aerotech. No credit will be given nor repairs made for products returned without such approval. A "Return Materials Authorization (RMA)" number must accompany any returned product(s). The RMA number may be obtained by calling an Aerotech service center or by submitting the appropriate request available on our website (www.aerotech.com). Products must be returned, prepaid, to an Aerotech service center (no C.O.D. or Collect Freight accepted). The status of any product returned later than thirty (30) days after the issuance of a return authorization number will be subject to review.

Visit <https://www.aerotech.com/global-technical-support.aspx> for the location of your nearest Aerotech Service center.

Returned Product Warranty Determination

After Aerotech's examination, warranty or out-of-warranty status will be determined. If upon Aerotech's examination a warranted defect exists, then the product(s) will be repaired at no charge and shipped, prepaid, back to the buyer. If the buyer desires an expedited method of return, the product(s) will be shipped collect. Warranty repairs do not extend the original warranty period.

Fixed Fee Repairs - Products having fixed-fee pricing will require a valid purchase order or credit card particulars before any service work can begin.

All Other Repairs - After Aerotech's evaluation, the buyer shall be notified of the repair cost. At such time the buyer must issue a valid purchase order to cover the cost of the repair and freight, or authorize the product(s) to be shipped back as is, at the buyer's expense. Failure to obtain a purchase order number or approval within thirty (30) days of notification will result in the product(s) being returned as is, at the buyer's expense.

Repair work is warranted for ninety (90) days from date of shipment. Replacement components are warranted for one year from date of shipment.

Rush Service

At times, the buyer may desire to expedite a repair. Regardless of warranty or out-of-warranty status, the buyer must issue a valid purchase order to cover the added rush service cost. Rush service is subject to Aerotech's approval.

On-site Warranty Repair

If an Aerotech product cannot be made functional by telephone assistance or by sending and having the customer install replacement parts, and cannot be returned to the Aerotech service center for repair, and if Aerotech determines the problem could be warranty-related, then the following policy applies:

Aerotech will provide an on-site Field Service Representative in a reasonable amount of time, provided that the customer issues a valid purchase order to Aerotech covering all transportation and subsistence costs. For warranty field repairs, the customer will not be charged for the cost of labor and material. If service is rendered at times other than normal work periods, then special rates apply.

If during the on-site repair it is determined the problem is not warranty related, then the terms and conditions stated in the following "On-Site Non-Warranty Repair" section apply.

On-site Non-Warranty Repair

If any Aerotech product cannot be made functional by telephone assistance or purchased replacement parts, and cannot be returned to the Aerotech service center for repair, then the following field service policy applies:

Aerotech will provide an on-site Field Service Representative in a reasonable amount of time, provided that the customer issues a valid purchase order to Aerotech covering all transportation and subsistence costs and the prevailing labor cost, including travel time, necessary to complete the repair.

Service Locations

<http://www.aerotech.com/contact-sales.aspx?mapState=showMap>

USA, CANADA, MEXICO	CHINA	GERMANY
Aerotech, Inc. Global Headquarters Phone: +1-412-967-6440 Fax: +1-412-967-6870	Aerotech China Full-Service Subsidiary Phone: +86 (21) 3319 7715	Aerotech Germany Full-Service Subsidiary Phone: +49 (0)911 967 9370 Fax: +49 (0)911 967 93720
JAPAN	TAIWAN	UNITED KINGDOM
Aerotech Japan Full-Service Subsidiary Phone: +81 (0)50 5830 6814 Fax: +81 (0)43 306 3773	Aerotech Taiwan Full-Service Subsidiary Phone: +886 (0)2 8751 6690	Aerotech United Kingdom Full-Service Subsidiary Phone: +44 (0)1256 855055 Fax: +44 (0)1256 855649

Have your customer order number ready before calling.

Appendix B: Revision History

Revision	Description
1.01.00	Product Update
1.00.00	New Manual

This page intentionally left blank.

Index

			I	
	2		Inertia	11
2010		6	inspect	29
	A		Inspection Schedule	29
Accuracy		10-11	isopropyl alcohol	30
Altitude		10		
Ambient Temperature		10	L	
Attaching the Payload to the Stage		17	label	13
Axial Error Motion		11	Load	11
	B		Load Capability	17
Bidirectional		11		
	C		M	
cleaning solvent		30	Mass	11
	D		Material	11
Drive System		11	Maximum Bus Voltag	11
	E		Maximum Load	11
Electrical Installation		19	Maximum Speed	11
Electrical Specifications			Maximum Torque (Continuous)	11
S-180		25	Motor Specifications	25
EN 60204-1		6	mounting surface	15
EN ISO 12100		6	Mounting Surface	15
Encoder		11		
Encoder Specifications		24	P	
	F		part number	13
Finish		11	Payload	17
	G		Performance Specifications	
Global Technical Support		2	S-180	25
	H		Protection Rating	10
Hall-Effect Sensors Specifications		24	protective ground connection	20
Handling the Stage		13		
Humidity		10	R	
			Radial Error Motion	11
			red, anodized aluminum	13
			Repeatability	11

S

S-180	
Electrical Specifications	25
Performance Specifications	25
S-180-44-A Slotless Motor	25
Securing the Stage to the Mounting Surface	15
serial number	13
Service and Inspection Schedule	29
Shimming	15
shipping clamps	13
solvents	30
stabilize	13
stage distortion	15
Support	2

T

Tabletop Diameter	11
Technical Support	2
Temperature	10
Thermistor Specifications	24
Tilt Error Motion	11
Travel	11

U

Unpacking and Handling the Stage	13
----------------------------------	----

V

Vibration	10
-----------	----

W

Warranty and Field Service	33
----------------------------	----