

GL4 HARDWARE MANUAL

Revision: 1.05.00





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Table of Contents

GL4 HARDWARE MANUAL	1
Table of Contents	3
List of Figures	4
List of Tables	5
EU Declaration of Conformity	7
Agency Approvals	9
Safety Procedures and Warnings	11
Quick Installation Guide	13
Chapter 1: Introduction	15
1.1. Electrical Specifications	17
1.2 Mechanical Specifications	18
1.2.1 Mounting and Cooling	18
122 Dimensions	19
1.3 Environmental Specifications	20
1.4 Drive and Software Compatibility	20
Chapter 2: Installation and Configuration	23
2.1. Input Power Connections	23
2.1.1. Control Supply Connector	23
2.1.2. Motor Supply Connector	24
2.1.3. External Power Supply Options	25
2.1.4. Minimizing Conducted, Radiated, and System Noise for EMC/CE Complia	ance 27
2.2. HyperWire Interface	
2.3. Laser Output Connectors	29
2.3.1. Position Synchronized Output (PSO)	34
2.4. Encoder Output Connector	35
2.5. Galvo Motor Connectors	37
2.5.1. Analog Encoder Inputs	
2.5.2. End of Travel Limit Input Interface	39
2.5.2.1. End of Travel Limit Phasing	41
2.5.3. Thermistor Input	42
2.6. Digital and Analog I/O Connectors	43
2.6.1. Digital Outputs	44
2.6.2. Digital Inputs	46
2.6.3. Analog Outputs	47
2.6.4. Analog Inputs (Differential)	48
2.7. Encoder Input Connectors	49
2.7.1. Emergency Stop Sense Input	51
2.8. Laser Output Polarity Switches	52
2.9. Sync Port	53
2.10. PC Configuration and Operation Information	54
Chapter 3: Maintenance	55
3.1 Dreventative Maintenance	55
3.2 Board Assembly	55 56
J.Z. Dualu Assembly	
Appendix A: Warranty and Field Service	59
Appendix B: Revision History	61
Index	63

List of Figures

Figure 1-1:	GL4 Networked Digital Galvo Controller		
Figure 1-2:	Functional Diagram		
Figure 1-3:	Dimensions		
Figure 2-1:	Control Supply Connections	23	
Figure 2-2:	Motor Supply Connections	.24	
Figure 2-3:	Control and Motor Power Wiring using a TM3 Transformer	.25	
Figure 2-4:	Third-Party Power Supply Connection	26	
Figure 2-5:	Laser Interface Outputs	30	
Figure 2-6:	Current Sinking Configuration with Isolation	.31	
Figure 2-7:	Current Sinking Configuration without Isolation	31	
Figure 2-8:	Current Sourcing Configuration with Isolation	32	
Figure 2-9:	Current Sourcing Configuration without Isolation	32	
Figure 2-10:	TTL Output	.33	
Figure 2-11:	Encoder Outputs	35	
Figure 2-12:	PSO External Sync Input	36	
Figure 2-13:	End of Travel Limit Input Connections	.40	
Figure 2-14:	End of Travel Limit Interface Input Schematic	40	
Figure 2-15:	Limit Input Diagnostic Display	41	
Figure 2-16:	Thermistor Input Input Schematic	.42	
Figure 2-17:	Digital Outputs Connected in Current Sourcing Mode	.45	
Figure 2-18:	Digital Outputs Connected in Current Sinking Mode	45	
Figure 2-19:	Digital Inputs Connected to Current Sinking Devices	46	
Figure 2-20:	20: Digital Inputs Connected to Current Sourcing Devices		
Figure 2-21:	Analog Outputs Schematic	47	
Figure 2-22:	Analog Inputs Schematic	48	
Figure 2-23:	Encoder Input Connections Schematic	.50	
Figure 2-24:	ESTOP Sense Input Schematic	51	
Figure 2-25:	Laser Output Polarity Switches	52	
Figure 3-1:	Control Board Assembly	56	
Figure 3-2:	Power Board Assembly	57	

List of Tables

Table 1-1:	Feature Summary	15	
Table 1-2:	Electrical Specifications		
Table 1-3:	Mounting Specifications	18	
Table 1-4:	Environmental Specifications		
Table 1-5:	Drive and Software Compatibility	21	
Table 2-1:	Control Supply Connector Wiring Specifications	23	
Table 2-2:	Mating Connector Part Numbers for the Control Supply Connector	23	
Table 2-3:	Motor Supply Wiring Specifications	24	
Table 2-4:	Mating Connector Part Numbers for the Motor Supply Connector	24	
Table 2-5:	HyperWire Card Part Number	28	
Table 2-6:	HyperWire Cable Part Numbers	28	
Table 2-7:	Laser Output Connector A Pinout	29	
Table 2-8:	Laser Output Connector B Pinout	29	
Table 2-9:	Mating Connector Part Numbers for the Laser Output Connectors	29	
Table 2-10:	Laser Output Specifications	30	
Table 2-11:	PSO Pins on the Laser Output A Connector	34	
Table 2-12:	PSO Pins on the Laser Output B Connector	34	
Table 2-13:	PSO Specifications	34	
Table 2-14:	Encoder Output Connector Pinout	35	
Table 2-15:	Mating Connector Part Numbers for the Encoder Output Connector	35	
Table 2-16:	PSO External Sync Specifications	36	
Table 2-17:	Galvo Motor Connectors Pinout	37	
Table 2-18:	Mating Connector Part Numbers for the Galvo Motor Connectors	37	
Table 2-19:	Analog Encoder Specifications	38	
Table 2-20:	End of Travel Limit Input Pins on the Galvo Motor Connectors	39	
Table 2-21:	Thermistor Input Pins on the Galvo Motor Connectors	42	
Table 2-22:	Digital and Analog I/O Connector A Pinout	43	
Table 2-23:	Digital and Analog I/O Connector B Pinout	43	
Table 2-24:	Mating Connector Part Numbers for the Digital / Analog I/O Connectors	43	
Table 2-25:	Digital Output Specifications	44	
Table 2-26:	Digital Output Pins on the Digital/Analog I/O A Connector	44	
Table 2-27:	Digital Input Specifications	46	
Table 2-28:	Digital Input Pins on the Digital/Analog I/O B Connector	46	
Table 2-29:	Analog Output Specifications	47	
Table 2-30:	Analog Output Pins on the Digital / Analog I/O B Connector	47	
Table 2-31:	Analog Input Specifications	48	
Table 2-32:	Analog Input Pins on the Digital / Analog I/O B Connector	48	
Table 2-33:	Encoder Input Specifications	49	
Table 2-34:	Axis 1 Encoder Input Pinout (Encoder Input Connector A)	49	
Table 2-35:	Axis 2 Encoder Input Pinout (Encoder Input Connector B)	49	
Table 2-36:	Mating Connector Part Numbers for the Encoder Input Connectors	49	
Table 2-37:	GL4 to Drive Cable Part Numbers	49	
Table 2-38:	ESTOP Pins on the Encoder Input Connector	51	
Table 2-39:		51	
1 able 2-40:	Sync-Related Commands	53	
Table 2-41:	Sync Port Cables	. 53	
Table 3-2:	Control Board Fuse Specifications		
i able 3-3:	Power Board Fuse Specifications	5/	

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EU Declaration of Conformity

Manufacturer	Aerotech, Inc.
Address	101 Zeta Drive
	Pittsburgh, PA 15238-2811
	USA
Product	GL4
Model/Types	All

This is to certify that the aforementioned product is in accordance with the applicable requirements of the following Directive(s):

2014/35/EU	Low Voltage Directive
EU 2015/863	RoHS 3 Directive

and has been designed to be in conformity with the applicable requirements of the following Standard(s) when installed and used in accordance with the manufacturer's supplied installation instructions.

EN 61010-1:2010 Safety Requirements for Electrical Equipment Authorized Representative: Simon Smith, European Director Address: Aerotech Ltd The Old Brick Kiln, Ramsdell, Tadley Hampshire RG26 5PR UK

(llog Threwood / Alex Weibel

Name Position Location Date

Engineer Verifying Compliance Pittsburgh, PA 4/27/2020

CE

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Agency Approvals

Aerotech tested its GL4 drives and found that they obey the standards that follow:

Approval / Certification:	CUSNRTL
Approving Agency:	TUV SUD America Inc.
Certificate #:	U8 16 06 68995 021
Standards:	CAN/CSA-C22.2 No. 61010-1:2012; EN 61010-1:2010; UL 61010-1:2012

Visit https://www.tuev-sued.de/product-testing/certificates to view Aerotech's TÜV SÜD certificates. Type the certificate number listed above in the search bar or type "Aerotech" for a list of all Aerotech certificates.

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Safety Procedures and Warnings

This manual tells you how to carefully and correctly use and operate the GL4. Read all parts of this manual before you install or operate the GL4 or before you do maintenance to your system. To prevent injury to you and damage to the equipment, obey the precautions in this manual. The precautions that follow apply when you see a Danger or Warning symbol in this manual. If you do not obey these precautions, injury to you or damage to the equipment can occur. If you do not understand the information in this manual, contact Aerotech Global Technical Support.

This product has been designed for light industrial manufacturing or laboratory environments. The protection provided by the equipment could be impaired if the product is used in a manner not specified by the manufacturer.

NOTE: All specifications and illustrations are for reference only and were complete and accurate as of the release of this manual. To find the newest information about this product, refer to www.aerotech.com.



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Quick Installation Guide

This image shows the order in which to make connections and settings that are typical to the GL4. If a custom interconnect drawing was supplied with your system, that drawing is on your Storage Device and shows as a line item on your Sales Order in the Integration section.



HyperWire	Section 2.2. HyperWire Interface	
Digital / Analog I/O	Section 2.6. Digital and Analog I/O Connectors	
Galvo Connections	Section 2.5. Galvo Motor Connectors	
Control Supply	ontrol Supply Section 2.1.1. Control Supply Connector	
Motor Supply	Section 2.1.2. Motor Supply Connector	

Figure 1: Quick Start Connections

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Chapter 1: Introduction

The GL4 is a closed-loop scanner module that lets you control servo motion from the galvo scanner to mark parts with no limit to size and complexity. The GL4 supports CO2 and YAG lasers and includes Position Synchronized Output (PSO) laser firing that uses real-time scanner positional feedback.



Figure 1-1: GL4 Networked Digital Galvo Controller

Standard Features	
 85-240 VAC; 50-60 Hz control supply 	Section 2.1.1.
 ±40 VDC max motor supply 	Section 2.1.2.
Two HyperWire ports	Section 2.2.
Three TTL laser outputs	Section 2.3.
Three optically-isolated laser outputs	Section 2.3.
Dual-Axis PSO firing	Section 2.3.1.
Three-axis Part-Speed PSO firing	Refer to the online Help
Two auxiliary channels of 40 MHz line driver quadrature encoder inputs	Section 2.7.
 Four optically-isolated digital outputs; 5-24V 	Section 2.6.1.
 Four optically-isolated digital inputs; 5-24V 	Section 2.6.2.
 Two 16-bit single-ended analog outputs; ±10 V 	Section 2.6.3.
 One 16-bit differential analog input; ±10 V 	Section 2.6.4.
 Dedicated 5-24V Emergency Stop sense input 	Section 2.7.1.
Two Sync ports	Section 2.9.



The block diagram that follows shows a summary of the connector signals.



1.1. Electrical Specifications

Table 1-2: Electrical Specifications

Description		GL4
Motor Supply	Input Voltage	±40 VDC (max)
	Input Current (continuous)	10 A
Control Supply	Input Voltage	85-240 VAC
	Input Frequency	50-60 Hz
	Inrush Current	16 A
	Input Current	0.35 A (max)
Output Voltage		38 V
Peak Output Current		20 A
Continuous Output Current		5 A
Minimum Load Resistance		0.5 Ω
User Power Supply Output		5 VDC (@ 500 mA)

1.2. Mechanical Specifications

1.2.1. Mounting and Cooling

Install the GL4 in an IP54 compliant enclosure to comply with safety standards. Make sure that there is sufficient clearance surrounding the drive for free airflow and for the cables and connections.

Table 1-3: Mounting Specifications

		GL4
Enclosure		IP54 Compliant
Weight		~2.9 kg
Mounting Hardware		M4 [#8] screws (four locations, not included)
Mounting Orientation		Vertical (typical)
Dimensions		Refer to Section 1.2.2. Dimensions
Minimum Clearance	Airflow	~25 mm
	Connectors	~100 mm
Operating Temperature		Refer to Section 1.3. Environmental Specifications

1.2.2. Dimensions





1.3. Environmental Specifications

	•
Ambient Temperature	Operating: 0° to 40°C (32° to 104° F)
Amplent remperature	Storage: -30° to 85°C (-22° to 185° F)
Humidity	The maximum relative humidity is 80% for temperatures that are less
Non-condensing	than 31°C and decreases linearly to 50% relative humidity at 40°C.
	0 m to 2,000 m (0 ft to 6,562 ft) above sea level.
Operating Altitude	If you must operate this product above 2,000 m or below sea level,
	contact Aerotech, Inc.
Pollution	Pollution Degree 2
Folloli	Typically only nonconductive pollution occurs.
Operation	Use only indoors

 Table 1-4:
 Environmental Specifications

1.4. Drive and Software Compatibility

This table shows the available drives and which version of the software first supported each drive. In the **Last Software Version** column, drives that show a specific version number are not supported after that version.

 Table 1-5:
 Drive and Software Compatibility

Drive Type	Firmware Revision	First Software Version	Last Software Version
GL4	-	6.04.000	Current

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Chapter 2: Installation and Configuration

2.1. Input Power Connections

The GL4 has two input power connectors. One connector is for AC control power and the other connector is for DC motor power. For a full list of electrical specifications, refer to Section 1.1.

2.1.1. Control Supply Connector

NOTE: To operate correctly, this product must have a power supply connected to the Motor Supply and a power supply connected to the Control Supply.

The Control Supply input supplies power to the communications and logic circuitry of the GL4. The AC1 input and the AC2 input are connected to fuses inside the GL4. Refer to Table 3-3 for fuse values and part numbers.

The Control Supply contains an internal filter. It is not necessary to use an external filter for CE compliance.

NOTE: Refer to local electrical safety requirements to correctly size external system wires.



DANGER: Before you operate the GL4, install a ground connection for your safety and to prevent damage to the equipment.



85-240V~ 50/60Hz 2A MAX

Figure 2-1: Control Supply Connections

Table 2-1: Control Supply Connector Wiring Specifications

Pin	Description	Recommended Wire Size ⁽¹⁾		
AC1	Line Input: 85 - 240 Volt AC Input Range	1.3 mm ² [#16 AWG]		
AC2	Neutral (0V) or 85 - 240 Volt AC Input Range	1.3 mm ² [#16 AWG]		
	Protective Ground	1.3 mm ² [#16 AWG]		
(1)The wire insulation is rated for 300 V.				

Table 2-2: Mating Connector Part Numbers for the Control Supply Connector

Туре	Aerotech P/N	Third Party P/N	Screw Torque Value: N·m	Wire Size: mm ² [AWG]
3-Pin Terminal Block	ECK00213	Phoenix 1754465	0.5 - 0.6	3.3 - 0.516 [12-30]

2.1.2. Motor Supply Connector

NOTE: To operate correctly, this product must have a power supply connected to the Motor Supply and a power supply connected to the Control Supply.

Motor power is applied to the GL4 at the four terminals of the Motor Supply connector. The DC+ input and the DC- input are connected to fuses inside the GL4. Refer to Table 3-3 for fuse values and part numbers.

NOTE: Refer to local electrical safety requirements to correctly size external system wires.

DANGER: To prevent the risk of electric shock, do not operate the GL4 without a ground connection.



Figure 2-2: Motor Supply Connections

Table 2-3: Motor Supply Wiring Specifications

Pin	Description	Recommended Wire Size ⁽¹⁾
DC+	+40 VDC Input Range	2.1 mm ² (#14 AWG)
RET	Return for DC Input	2.1 mm ² (#14 AWG)
DC-	-40 VDC Input Range	2.1 mm ² (#14 AWG)
	Protective Ground	2.1 mm ² (#14 AWG)
(4) 71		

(1)The wire insulation is rated for 300 V.

Table 2-4: Mating Connector Part Numbers for the Motor Supply Connector

Туре	Aerotech P/N	Third Party P/N	Screw Torque Value: N·m	Wire Size: mm ² [AWG]
4-Pin Terminal Block	ECK01581	Phoenix 1757035	0.5 - 0.6	3.3 - 0.0516 [12-30]

2.1.3. External Power Supply Options

You must connect the Motor Supply to a bipolar power supply. Aerotech recommends that you use an Aerotech TM3 transformer which can supply power to a maximum of four controllers. Refer to Figure 2-3.

As an alternative to a bipolar power supply, you can use two third-party power supplies but they must obey these conditions. Refer to Figure 2-4.

- The output of each power supply must not be ground referenced.
- The output of each power supply must be specified to be used in positive or negative polarity.

The GL4 controller can source 10 A peak current to each motor. This current must be supplied by the external power supply. A switching power supply must be rated for the peak current requirement of the system because the switching power supply might shut down if it is overloaded.



Figure 2-3: Control and Motor Power Wiring using a TM3 Transformer



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2.1.4. Minimizing Conducted, Radiated, and System Noise for EMC/CE Compliance

NOTE: The GL4 is a component designed to be integrated with other electronics. EMC testing must be conducted on the final product configuration.

To reduce electrical noise, observe the following motor and input power wiring techniques.

- 1. Separate motor and power wiring from encoder and I/O wiring.
- 2. Mount drives, power supplies, and filter components on a conductive panel. Mount line filters close to the drive to keep the wire length between the drive and filter to a minimum. Use a line filter, such as Aerotech's UFM-ST, on the Control Supply AC inputs.

The following additional changes could be required for EMC compliance and are recommended during initial EMC system evaluation.

- 1. Add a clamp-on ferrite to the motor feedback cable close to the drive. [Aerotech PN ECZ02348, Fair-rite PN 0446167281]
- 2. Add a ferrite core to the UFM-ST AC input wires. Wrap the AC wires and ground wire around the core one time.

[Ferrite core: Aerotech PN ECZ02350, Fair-rite PN 2646102002]

2.2. HyperWire Interface

The HyperWire bus is the high-speed communications connection to the GL4 operating at 2 gigabits per second. The PC sends all command and configuration information through the HyperWire bus.

Table 2-5: HyperWire Card Part Number

Part Number	Description
HYPERWIRE-PCIE	HyperWire adapter, PCIe x4 interface

Table 2-6: HyperWire Cable Part Numbers

Part Number	Description
HYPERWIRE-AO10-5	HyperWire cable, active optical, 0.5 m
HYPERWIRE-AO10-10	HyperWire cable, active optical, 1.0 m
HYPERWIRE-AO10-30	HyperWire cable, active optical, 3.0 m
HYPERWIRE-AO10-50	HyperWire cable, active optical, 5.0 m
HYPERWIRE-AO10-200	HyperWire cable, active optical, 20.0 m

2.3. Laser Output Connectors

The Laser Output has two 7-pin terminal block-style connectors and supplies connections to the laser control outputs. Three laser output signals are available as optically-isolated or as 5V TTL signals. You can wire the optically-isolated outputs in a sourcing or sinking configuration.

To set the active polarity of the laser output signals, use the switches on the top of the GL4. Refer to Section 2.8.

To turn on the output and activate the laser, move the switch to the **OFF** position. This is the Normally-Open configuration. The laser output is fully turned on when one of these conditions occurs.

- The optically-isolated output conducts current.
- The TTL output is 5 V.

To select the opposite polarity, move the switch to the **ON** position. This is the Normally-Closed configuration. When the GL4 is powered off, it does not continue to support this configuration. This configuration is not a fail-safe feature.



WARNING: After you install this product, you must tell the operator about all applicable safety conditions and safety information. Refer the operator to the laser manual for safety information about the laser.

 Table 2-7:
 Laser Output Connector A Pinout

Pin #	Label	Description	In/Out/Bi	Connector	
1	01+	Laser Output 1+ / PSO Output ⁽¹⁾	Output		
2	01-	Laser Output 1- / PSO Output ⁽¹⁾	Output	01 +	
3	O2+	Laser Output 2+	Output	01 - 02 +	
4	02-	Laser Output 2-	Output	02 -	
5	O3+	Laser Output 3+	Output	03 +	
6	O3-	Laser Output 3-	Output		
7	GND	Ground			
(1) Refe	(1) Befer to Section 2.3.1 for more information				

 Table 2-8:
 Laser Output Connector B Pinout

Pin #	Label	Description	In/Out/Bi	Connector	
1	01	Laser Output 1 / PSO Output ⁽¹⁾ (5V TTL)	Output		
2	GND	Ground		01	
3	02	Laser Output 2 (5V TTL)	Output	GND 02	
4	GND	Ground		• III • GND	
5	O3	Laser Output 3 (5V TTL)	Output	03	
6	GND	Ground		GND +5V	
7	+5V	5 Volt Power Supply (500 mA)	Output	.34	
(1) Refer	(1) Pofer to Section 2.3.1 for more information				

(1) Refer to Section 2.3.1. for more information

Table 2-9: Mating Connector Part Numbers for the Laser Output Connectors

Туре	Aerotech P/N	Third Party P/N	Wire Size: mm ² [AWG]
7-Pin Terminal Block	ECK01631	Phoenix 1881370	0.5 - 0.080 [20-28]

	Specification	Value
loolotod	Maximum Frequency	5 MHz
Output	Voltage	5 - 24 V
Output	Output Current	≤ 50 mA
	Maximum Frequency	10 MHz
5V TTL	Voltage	5 V
	Output Current	50 mA

Table 2-10: Laser Output Specifications







Figure 2-6: Current Sinking Configuration with Isolation



Figure 2-7: Current Sinking Configuration without Isolation



Figure 2-8: Current Sourcing Configuration with Isolation







Figure 2-10: TTL Output

2.3.1. Position Synchronized Output (PSO)

You can program the Position Synchronized Output (PSO) to generate an output that is synchronized to the feedback position of an axis. PSO is typically used to fire a laser or trigger an external hardware device.

A PSO firing event can be triggered from a feedback channel or from a software trigger. You can get quadrature signals from feedback channels and PSO firing event signals after a PSO firing event occurs. When the PSO generates pulses, minimum latency occurs between the trigger condition and the output.

Aerotech recommends that you use an RS-422 line receiver or an opto-isolator if your system:

- Uses cables with long lengths in work areas where a lot of electrical noise occurs.
- Uses high-frequency pulse transmission.

For best performance, put the RS-422 line receiver or the opto-isolator near the electronics that receive the PSO output pulse.

Table 2-11: PSO Pins on the Laser Output A Connector

Pin #	Label	Description	In/Out/Bi
1	01+	Laser Output 1+ / PSO Output	Output
2	01-	Laser Output 1- / PSO Output	Output

Table 2-12: PSO Pins on the Laser Output B Connector

Pin #	Label	Description	In/Out/Bi
1	01	Laser Output 1 / PSO Output (5V TTL)	Output
2	GND	Ground	

Table 2-13:PSO Specifications

Specification		Value
Movimum BSO Output (Eiro) Eroquopov	TTL	12.5 MHz
Maximum PSO Output (Fire) Frequency	Isolated	5 MHz
Output Latency	TTL	50 ns
[Fire event to output change]	Isolated	150 ns
1. Signals in excess of this rate will cause a loss of PSO accuracy		

2.4. Encoder Output Connector

The Encoder Output interface echos the encoder signals out of the two axes.

Table 2-14: Encoder Output Connector Pinout

Pin	Description	In/Out/Bi	Connector
1	Axis 1 SIN-	Output	
2	Reserved		
3	Axis 1 COS-	Output	
4	Axis 2 SIN-	Output	
5	Axis 2 COS-	Output	
6	Reserved		
7	PSO External Sync	Input	ĬŠŠ
8	+5V	Output	
9	Axis 1 SIN+	Output	
10	Reserved		9 1
11	Axis 1 COS+	Output	
12	Axis 2 SIN+	Output	
13	Axis 2 COS+	Output	
14	Reserved		
15	Ground		

 Table 2-15:
 Mating Connector Part Numbers for the Encoder Output Connector

Mating Connector	Aerotech P/N	Third Party P/N
15-Pin D-Connector	ECK00100	Amphenol DA15P064TXLF
Backshell	ECK01022	Amphenol 17E-1725-2



Figure 2-11: Encoder Outputs

Specification	Value
Voltage	3.3 VDC
Frequency	25 MHz Maximum
On Time	20 ns Minimum





Figure 2-12: PSO External Sync Input

2.5. Galvo Motor Connectors

The GL4 is configured for AGV galvo motors at the factory. You cannot use the GL4 with other types of motors. AGV galvo motors operate as DC Brush motors over a limited travel.

Each galvo motor connector is a 25-pin, D-style connector that has two analog encoder inputs, 5 V encoder power, and galvo motor connections.

Pin	Description	In/Out/Bi	Pin Location
1	Sine 1+	Input	
2	Cosine 1+	Input	
3	Encoder Ground		
4	Sine 2+	Input	
5	Cosine 2+	Input	
6	Clockwise End of Travel Limit	Input	\bigcirc
7	Marker 1+	Input	12
8	Encoder Power (+5V, 500 mA)	Output	25
9	Motor Over Temperature Thermistor	Input	••
10	Flash Configuration	Input	• •
11	Frame Ground		• •
12	Motor +	Output	•••
13	Motor +	Output	••
14	Sine 1-	Input	• •
15	Cosine 1-	Input	• •
16	Encoder Ground		•
17	Sine 2-	Input	•••
18	Cosine 2-	Input	14
19	Counterclockwise End of Travel Limit	Input	
20	Marker 1-	Input	\bigcirc
21	Encoder Ground		
22	Encoder Ground		
23	Frame Ground		
24	Motor -	Output	
25	Motor -	Output	

 Table 2-17:
 Galvo Motor Connectors Pinout

Table 2-18:	Mating Connector Part Numbers for the Galvo Motor Connector	rs
-------------	---	----

Mating Connector	Aerotech P/N	Third Party P/N
25-Pin D-Connector	ECK00101	FCI DB25P064TXLF
Backshell	ECK00656	Amphenol 17E-1726-2

2.5.1. Analog Encoder Inputs

The GL4 has two analog encoder input channels for each galvo connector. The GL4 uses these input channels for position feedback.

Use the Feedback Tuning tab of Digital Scope to automatically adjust the value of the gain, offset, and phase balance controller parameters to get the best performance. For more information, refer to the Help file.

Table 2-19: Analog Encoder Specifications

Specification	Value	
Input Frequency (max)	500 kHz	
Input Amplitude ⁽¹⁾	0.6 to 1.2 Vpk-pk	
Interpolation Factor (max)	262,144	
Input Common Mode	1.5 to 3.5 VDC	
(1) Any single-ended encoder signal measured with respect to ground.		

2.5.2. End of Travel Limit Input Interface

Aerotech strongly recommends that you use End of Travel (EOT) limits to define the end of the physical travel. Current-based limits that are software-selectable through the EndOfTravelLimitSetup axis parameter can be used, but only if EOT limits are not available on your galvo motor. Positive or clockwise motion is stopped by the clockwise (CW) end of travel limit input. Negative or counterclockwise motion is stopped by the counterclockwise (CCW) end of travel limit input. The Home Limit switch can be parameter configured for use during the home cycle, however, the CW or CCW EOT limit is typically used instead. All of the end-of-travel limit inputs accept 0-5 VDC level signals. Limit directions are relative to the encoder polarity in the diagnostics display (refer to Figure 1-1).

Pin	Description	In/Out/Bi
6	Clockwise End of Travel Limit	Input
8	Encoder Power (+5V, 500 mA)	Output
16	Encoder Ground	
19	Counterclockwise End of Travel Limit	Input

Table 2-20:	End of Travel Limit Input Pins on the Galvo Motor Connectors
	End of flator Enfittingation and on the Garto Motor Connectore

Aerotech recommends that you use a normally-closed limit switch and select Active High for this option. This configuration provides fail-safe limit behavior because the controller generates a fault if the external hardware is not connected or is not operating correctly. If you connect a normally-closed limit switch between the limit input and limit common and the switch is not activated, it stays closed and the limit inputs are pulled low by the limit switch. When the switch is activated, it opens and the limit input is pulled high by the circuit inside the drive.

The active state of the EOT limits is software selectable (by the EndOfTravelLimitSetup axis parameter). Figure 2-13 shows the possible wiring configurations for normally-open and normally-closed switches and the parameter setting to use for each configuration.







Figure 2-14: End of Travel Limit Interface Input Schematic

2.5.2.1. End of Travel Limit Phasing

If the EOT limits are reversed, you will be able to move further into a limit but be unable to move out. To correct this, swap the connections to the CW and CCW inputs at the motor feedback connector or swap the CW and CCW limit functionality in the software using the EndOfTravelLimitSetup parameter. The logic level of the EOT limit inputs may be viewed in the diagnostic display (shown in Figure 2-15).

Export 💱 Settings					
Polling rate: Medium 🔻	Diagnostics				
Axes	Item	X	Y	Z*	
Axis Status Diagnostics	Auxiliary Position Feedback	00000000000	000000000000	00000000000	
Drive Into	Analog Input 0	0.0000	0.0000	0.000	
Fault	Analog Input 1	0.0000	0.0000	0.000	
 Tasks 	Digital Input 15:0	0000 0000 0000 0000	0000 0000 0000 0000	0000 0000 0000 000	
Task Mode	Digital Input 31:10	0000 0000 0000 0000	0000 0000 0000 0000	0000 0000 0000 000	
Task Status 0	Digital Output 15:0	0000 0000 0000 0000	0000 0000 0000 0000	0000 0000 0000 000	
Task Status 1 Task Status 2	Digital Output 31:16	0000 0000 0000 0000	0000 0000 0000 0000	0000 0000 0000 000	
Tasks	Average Velocity Feedback	000000000000000000000000000000000000000	000000000000000000000000000000000000000	000000000000000000000000000000000000000	
Controller	Current Feedback	0.0000	0.0000	0.000	
Data Collection	Transition Offset Errors	U	0		
Drive Nodes	Hardware				
Ethernet	Enable			· E	
	CW				
	CCW				
	Home				
	Marker				
	Hall A				
	Hall B				
	Hall C			•	
	ESTOP				
	Brake			Ŧ	
	<			Þ	

Figure 2-15: Limit Input Diagnostic Display

2.5.3. Thermistor Input

The thermistor input is used to detect a motor over temperature condition by using a negative temperature coefficient sensor. As the temperature of the sensor increases, the resistance decreases. Under normal operating conditions, the resistance of the thermistor is high (i.e., $10 \text{ k}\Omega$) which will result in a high input signal. As the increasing temperature causes the thermistor's resistance to decrease, the signal will be seen as a logic low triggering an over temperature fault. The nominal trip value of the sensor is 2.4 k Ω .

Table 2-21:	Thermistor In	out Pins on	the Galvo	Motor Conne	ectors
	Thermistor in				501013



Figure 2-16: Thermistor Input Input Schematic

2.6. Digital and Analog I/O Connectors

This connector has four digital, optically-isolated outputs, four digital, optically-isolated inputs, one differential analog input, and two analog outputs.

		3 • • • • 3 • • • • • • • • • • • • • • • • • • •		
Pin #	Label	Description	In/Out/Bi	Connector
1	DO0	Digital Output 0 (Optically-Isolated)	Output	
2	D01	Digital Output 1 (Optically-Isolated)	Output	DO 0
3	DO2	Digital Output 2 (Optically-Isolated)	Output	
4	DO3	Digital Output 3 (Optically-Isolated)	Output	DO 3
5	DOC	Digital Output Common	Input	DOC O
6	Al+	Analog Input +	Input	
7	Al-	Analog Input -	Input	GND OT D
8	GND	Ground		

Table 2-22: Digital and Analog I/O Connector A Pinout

Table 2-23: Digital and Analog I/O Connector B Pinout

Pin #	Label	Description	In/Out/Bi	Connector
1	DI0	Digital Input 0 (Optically-Isolated)	Input	
2	DI1	Digital Input 1 (Optically-Isolated)	Input	DI 0
3	DI2	Digital Input 2 (Optically-Isolated)	Input	
4	DI3	Digital Input 3 (Optically-Isolated)	Input	• • DI 3
5	DIC	Digital Input Common	Input	O DI C
6	AO0	Analog Output 0	Output	A0 0
7	AO1	Analog Output 1	Output	+5V
8	+5V	+5V	Input	

Table 2-24: Mating Connector Part Numbers for the Digital / Analog I/O Connectors

Mating Connector	Aerotech P/N	Third Party P/N	Wire Size: mm ² [AWG]
8-Pin Terminal Block	ECK01386	Phoenix 1881383	0.5 - 0.080 [20-28]

2.6.1. Digital Outputs

Optically-isolated solid-state relays drive the digital outputs. You can connect the digital outputs in current sourcing or current sinking mode but you must connect all four outputs in the same configuration. Refer to Figure 2-17 and Figure 2-18.

You must install suppression diodes on digital outputs that drive relays or other inductive devices. To see an example of a current sourcing output that has diode suppression, refer to Figure 2-17. To see an example of a current sinking output that has diode suppression, refer to Figure 2-18

The digital outputs are not designed for high-voltage isolation applications and they should only be used with ground-referenced circuits.

NOTE: The digital outputs have overload protection. They will resume normal operation when the overload is removed.

Table 2-25: Digital Output Specifications

Digital Output Specifications	Value
Maximum Voltage	24 V (26 V Maximum)
Maximum Sink/Source Current	50 mA/output
Output Saturation Voltage	0.2 V at maximum current
Output Resistance	4 Ω
Rise / Fall Time	250 μs (2K pull up to 24V)
Reset State	Output Off (High Impedance State)

Table 2-26: Digital Output Pins on the Digital/Analog I/O A Connector

Pin #	Label	Description	In/Out/Bi
1	DO0	Digital Output 0 (Optically-Isolated)	Output
2	DO1	Digital Output 1 (Optically-Isolated)	Output
3	DO2	Digital Output 2 (Optically-Isolated)	Output
4	DO3	Digital Output 3 (Optically-Isolated)	Output
5	DOC	Digital Output Common	Input



🔬 Each output 50 mA maximum

2 Diode required on each output that drives an inductive device (coil), such as a relay.







2.6.2. Digital Inputs

You can connect the digital inputs to current sourcing or current sinking devices but you must connect all four inputs in the same configuration. Refer to Figure 2-20 and Figure 2-19. The digital inputs are not designed for high-voltage isolation applications. They should only be used with ground-referenced circuits.

Table 2-27. Digital input opecifications
--

Input Voltage	Approximate Input Current	Turn On Time	Turn Off Time
+5 V to +24 V	6 mA	10 µs	43 µs

Table 2-28:	Digital Input Pins on the Digital/Analog I/O B Connector
-------------	--

Pin #	Label	Description	In/Out/Bi
1	DI0	Digital Input 0 (Optically-Isolated)	Input
2	DI1	Digital Input 1 (Optically-Isolated)	Input
3	DI2	Digital Input 2 (Optically-Isolated)	Input
4	DI3	Digital Input 3 (Optically-Isolated)	Input
5	DIC	Digital Input Common	Input









2.6.3. Analog Outputs

The analog output is set to zero when you power on the system or reset the drive.

 Table 2-29:
 Analog Output Specifications

Specification	Value
Output Voltage	-10 V to +10 V
Output Current	5 mA
Resolution (bits)	16 bits

Table 2-30: Analog Output Pins on the Digital / Analog I/O B Connector

Pin #	Label	Description	In/Out/Bi
6	AO0	Analog Output 0	Output
7	AO1	Analog Output 1	Output



Figure 2-21: Analog Outputs Schematic

2.6.4. Analog Inputs (Differential)

To interface to a single-ended, non-differential voltage source, connect the signal common of the source to the negative input and connect the analog source signal to the positive input. A floating signal source must be referenced to the analog common. Refer to Figure 2-22.

Table 2-31: Analog Input Specifications

Specification	Value			
(AI+) - (AI-)	+10 V to -10 V ⁽¹⁾			
Resolution (bits)	16 bits			
Input Impedance 1 MΩ				
1. Signals outside of this range may damage the input				

Table 2-32: Analog Input Pins on the Digital / Analog I/O B Connector

Pin #	Label	Description	In/Out/Bi
6	Al+	Analog Input +	Input
7	Al-	Analog Input -	Input
8	GND	Ground	



Figure 2-22: Analog Inputs Schematic

2.7. Encoder Input Connectors

The GL4 has two auxiliary encoder input channels. Each encoder interface accepts an RS-422 differential line driver. Use the auxiliary encoder input channels with the Infinite Field of View (IFOV) and the "Marking on the Fly" functionality of the GL4. You cannot use the auxiliary encoder input channels to close the position loop.

Table 2-33: Encoder Input Specifications

Specification	Value	
Encoder Frequency	10 MHz maximum (25 ns minimum edge separation)	
x4 Quadrature Decoding	40 million counts/sec	

Table 2-34: Axis 1 Encoder Input Pinout (Encoder Input Connector A)

Pin	Label	Description	In/Out/Bi	Connector
1	SIN1+	Encoder SIN+ Input	Input	
2	SIN1-	Encoder SIN- Input	Input	SIN1+
3	COS1+	Encoder COS+ Input	Input	COS1+
4	COS1-	Encoder COS- Input	Input	COS1-
5	ESTOP+	Emergency Stop Digital Input +	Input	ESTOP+
6	ESTOP-	Emergency Stop Digital Input -	Input	

Table 2-35: Axis 2 Encoder Input Pinout (Encoder Input Connector B)

Pin	Label	Description	In/Out/Bi	Connector
1	SIN2+	Encoder SIN+ Input	Input	
2	SIN2-	Encoder SIN- Input	Input	SIN2 +
3	COS2+	Encoder COS+ Input	Input	SIN2 -
4	COS2-	Encoder COS- Input	Input	COS2-
5	+5V	+5V Encoder Power	Output	+5V
6	GND	Ground		GND

Table 2-36: Mating Connector Part Numbers for the Encoder Input Connectors

Туре	Aerotech P/N	Third Party P/N	Wire Size: mm ² [AWG]
6-Pin Terminal Block	ECK02220	Phoenix 1881367	0.5 - 0.080 [20-28]

Table 2-37: GL4 to Drive Cable Part Numbers

Drive Type	Cable P/N
XR3	C26263-xx
XC2/XC2e	C25483-xx
Sync-Supported Drives (for example: XC4, XC4e)	Refer to Section 2.9. Sync Port



Figure 2-23: Encoder Input Connections Schematic

2.7.1. Emergency Stop Sense Input

WARNING: It is your responsibility to assemble the external safety circuits of your system to minimize the risk to the operator.

NOTE: The ESTOP sense input is not a safety-rated system.

Use the ESTOP sense input to monitor the state of an external safety circuit only. The software identifies this state by using the **Emergency Stop Input Level** bit of the Drive Status. To get the software to generate an ESTOP fault when power is removed at the ESTOP input, set the ESTOP bit in the FaultMask parameter.

The ESTOP input is scaled for an input voltage of 5 - 24 volts.



Figure 2-24: ESTOP Sense Input Schematic

Table 2-38:	ESTOP	Pins on	the Encoder	r Input Connecto	r
-------------	-------	---------	-------------	------------------	---

Pin #	Label	Description	In/Out/Bi
5	ESTOP+	Emergency Stop Digital Input +	Input
6	ESTOP-	Emergency Stop Digital Input -	Input

NOTE: If you connect the ESTOP input to a device that makes electrical noise, you must connect an electrical noise suppression device across the switched coil. Refer to Table 2-39 to see the types of devices you can use.

Table 2-55. Electrical Noise Suppression Device.	Table 2-39:	Electrical	Noise	Suppression	Devices
--	-------------	------------	-------	-------------	----------------

Device	Aerotech P/N	Third Party P/N
RC (.1uf / 200 ohm) Network	EIC00240	Electrocube RG1782-8
Varistor	EID00160	Littelfuse V250LA40A

2.8. Laser Output Polarity Switches

Use the Laser Output Polarity switches to specify the active laser output polarity. Refer to Section 2.3.



Figure 2-25: Laser Output Polarity Switches

2.9. Sync Port

The Sync port is a bi-directional high speed proprietary interface that lets you transmit encoder signals between drives. This is typically used for multi-axis PSO applications where one or two drives send their encoder signals to a main drive that has the PSO logic and PSO output signal. The GL4 contains two Sync ports, labeled A and B.

To avoid signal contention, all Sync ports default to the input state during reset and immediately after power is applied to the drive.

Table 2-40: Sync-Related Commands				
Command	Desciption			
ENCODER OUT	Configure each Sync port as an input or an output			
PSOTRACK INPUT	Lat the BSO to track the SYNC A or SYNC P part			
PSOWINDOW INPUT	Let the PSO to track the STNC A of STNC B port.			

Table 2-40: Sync-Related Commands

The Sync port uses low-voltage differential signaling (LVDS) and standard USB 3.0 type A (cross over) cables.

Table 2-41:Sync Port Cables

Part Number	Desciption
CBL-SYNC-3	Length 3 dm; Connectors: USB Type A to USB Type A
CBL-SYNC-5	Length 5 dm; Connectors: USB Type A to USB Type A
CBL-SYNC-7	Length 7 dm; Connectors: USB Type A to USB Type A
CBL-SYNC-10	Length 10 dm; Connectors: USB Type A to USB Type A

2.10. PC Configuration and Operation Information

For more information about hardware requirements, PC configuration, programming, system operation, and utilities, refer to the Help file.

Chapter 3: Maintenance

DANGER: Before you open the GL4 chassis, you must disconnect the Mains power connection.



DANGER: All tests must be done by an approved service technician. Voltages inside the controller and at the input and output power connections can kill you.

3.1. Preventative Maintenance

Do an inspection of the GL4 and the external wiring one time each month. It might be necessary to do more frequent inspections based on:

- The operating conditions of the system.
- How you use the system.

Table 3-1: Preventative Maintenance

Check	Action to be Taken
Examine the chassis for hardware and parts that are damaged or loose. It is not necessary to do an internal inspection unless you think internal damage occurred.	Repair all damaged parts.
Do an inspection of the cooling vents.	Remove all material that collected in the vents.
Examine the work area to make sure there are no fluids and no electrically conductive materials.	Do not let fluids and electrically conductive material go into the GL4.
Examine all cables and connections to make sure they are correct.	Make sure that all connections are correctly attached and not loose. Replace cables that are worn. Replace all broken connectors.

Cleaning

DANGER: Before you clean the GL4, disconnect the electrical power from the drive.

Use a clean, dry, soft cloth to clean the chassis of the GL4. If necessary, you can use a cloth that is moist with water or isopropyl alcohol. If you use a moist cloth, make sure that moisture does not go into the GL4. Also make sure that it does not go onto the outer connectors and components.

Do not use fluids and sprays to clean the GL4 because they can easily go into the chassis or onto the outer connectors and components. If a cleaning solution goes into the GL4, internal contamination can cause corrosion and electrical short circuits.

Do not clean the labels with a cleaning solution because it might remove the label information.

3.2. Board Assembly

Figure 3-1 highlights the important components located on the control board.

DANGER: Before you open the GL4 chassis, you must disconnect the Mains power connection.



Figure 3-1: Control Board Assembly

Table 3-2:	Control	Board Fuse	Specifications
------------	---------	-------------------	----------------

Fuse	Description	Size	Aerotech P/N	Third Party P/N	
F1	F1 Control Supply Power at Pin-1		EIF01048	Littelfuse 0875002.MXEP	
F2 Control Supply Power at Pin-1		2 A S.B.	EIF01048	Littelfuse 0875002.MXEP	
F6	HyperWire power				
NOTE: F6 is a resettable fuse. It is not necessary to replace the fuse. Turn off the power and remove the short circuit.					



Figure 3-2: Power Board Assembly

Fuse	Description	Size	Aerotech P/N	Third Party P/N	
F1	Motor Bus Supply	10 A S.B.	EF01020	Littelfuse 215010.P	
F2	Motor Bus Supply	10 A S.B.	EF01020	Littelfuse 215010.P	
NOTE: F1 and F2 are on the bottom of the board.					

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Appendix A: Warranty and Field Service

Aerotech, Inc. warrants its products to be free from harmful defects caused by faulty materials or poor workmanship for a minimum period of one year from date of shipment from Aerotech. Aerotech's liability is limited to replacing, repairing or issuing credit, at its option, for any products that are returned by the original purchaser during the warranty period. Aerotech makes no warranty that its products are fit for the use or purpose to which they may be put by the buyer, whether or not such use or purpose has been disclosed to Aerotech in specifications or drawings previously or subsequently provided, or whether or not Aerotech's liability on any claim for loss or damage arising out of the sale, resale, or use of any of its products shall in no event exceed the selling price of the unit.

THE EXPRESS WARRANTY SET FORTH HEREIN IS IN LIEU OF AND EXCLUDES ALL OTHER WARRANTIES, EXPRESSED OR IMPLIED, BY OPERATION OF LAW OR OTHERWISE. IN NO EVENT SHALL AEROTECH BE LIABLE FOR CONSEQUENTIAL OR SPECIAL DAMAGES.

Return Products Procedure

Claims for shipment damage (evident or concealed) must be filed with the carrier by the buyer. Aerotech must be notified within thirty (30) days of shipment of incorrect material. No product may be returned, whether in warranty or out of warranty, without first obtaining approval from Aerotech. No credit will be given nor repairs made for products returned without such approval. A "Return Materials Authorization (RMA)" number must accompany any returned product(s). The RMA number may be obtained by calling an Aerotech service center or by submitting the appropriate request available on our website (www.aerotech.com). Products must be returned, prepaid, to an Aerotech service center (no C.O.D. or Collect Freight accepted). The status of any product returned later than thirty (30) days after the issuance of a return authorization number will be subject to review.

Visit https://www.aerotech.com/global-technical-support.aspx for the location of your nearest Aerotech Service center.

Returned Product Warranty Determination

After Aerotech's examination, warranty or out-of-warranty status will be determined. If upon Aerotech's examination a warranted defect exists, then the product(s) will be repaired at no charge and shipped, prepaid, back to the buyer. If the buyer desires an expedited method of return, the product(s) will be shipped collect. Warranty repairs do not extend the original warranty period.

Fixed Fee Repairs - Products having fixed-fee pricing will require a valid purchase order or credit card particulars before any service work can begin.

All Other Repairs - After Aerotech's evaluation, the buyer shall be notified of the repair cost. At such time the buyer must issue a valid purchase order to cover the cost of the repair and freight, or authorize the product(s) to be shipped back as is, at the buyer's expense. Failure to obtain a purchase order number or approval within thirty (30) days of notification will result in the product(s) being returned as is, at the buyer's expense.

Repair work is warranted for ninety (90) days from date of shipment. Replacement components are warranted for one year from date of shipment.

Rush Service

At times, the buyer may desire to expedite a repair. Regardless of warranty or out-of-warranty status, the buyer must issue a valid purchase order to cover the added rush service cost. Rush service is subject to Aerotech's approval.

On-site Warranty Repair

If an Aerotech product cannot be made functional by telephone assistance or by sending and having the customer install replacement parts, and cannot be returned to the Aerotech service center for repair, and if Aerotech determines the problem could be warranty-related, then the following policy applies:

Aerotech will provide an on-site Field Service Representative in a reasonable amount of time, provided that the customer issues a valid purchase order to Aerotech covering all transportation and subsistence costs. For warranty field repairs, the customer will not be charged for the cost of labor and material. If service is rendered at times other than normal work periods, then special rates apply.

If during the on-site repair it is determined the problem is not warranty related, then the terms and conditions stated in the following "On-Site Non-Warranty Repair" section apply.

On-site Non-Warranty Repair

If any Aerotech product cannot be made functional by telephone assistance or purchased replacement parts, and cannot be returned to the Aerotech service center for repair, then the following field service policy applies:

Aerotech will provide an on-site Field Service Representative in a reasonable amount of time, provided that the customer issues a valid purchase order to Aerotech covering all transportation and subsistence costs and the prevailing labor cost, including travel time, necessary to complete the repair.

Service Locations

http://www.aerotech.com/contact-sales.aspx?mapState=showMap

USA, CANADA, MEXICO	CHINA	GERMANY
Aerotech, Inc.	Aerotech China	Aerotech Germany
Global Headquarters	Full-Service Subsidiary	Full-Service Subsidiary
Phone: +1-412-967-6440 Fax: +1-412-967-6870	Phone: +86 (21) 5508 6731	Phone: +49 (0)911 967 9370 Fax: +49 (0)911 967 93720

TAIWAN	UNITED KINGDOM	
Aerotech Taiwan	Aerotech United Kingdom	
Full-Service Subsidiary	Full-Service Subsidiary	
Phone: +886 (0)2 8751 6690	Phone: +44 (0)1256 855055	
	Fax: +44 (0)1256 855649	

Have your customer order number ready before calling.

Appendix B: Revision History

Revision	Description		
1.05.00	Updated Section 1.2. Mechanical Specifications		
	Added cable part numbers: Table 2-37		
1.03.00	Updated to AUTOMATION1 hardware		
1.02.00	Added Table 2-16		
	The following sections have been updated:		
1 01 00	General product update		
1.01.00	 Section 2.1.4. Minimizing Conducted, Radiated, and System Noise for 		
	EMC/CE Compliance		
1.00.00	New Manual		

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In	dex		cables, examining	55
	2		CAN/CSA-C22.2 No. 61010-1	9
2	2014/35/EU	7	Check for fluids or electrically conductive material exposure	55
	Α		Cleaning	55
A	Agency Approvals	9	Commands	
A	Altitude	20	Sync	53
A	Ambient Temperature	20	connections, examining	55
A	Analog Encoder Inputs (Galvo Motor Connectors)	38	Continuous Output Current	17
A	Analog Encoder Specifications (Galvo Motor Connectors)	38	Control and Motor Power Wiring using a TM3 Transformer	25
۵	Analog Input Pins on the Digital / Analog I/O P		Control Board Assembly	56
,	Connector	48	Control Board Fuse Specifications	56
A	Analog Input Specifications (Digital / Analog I/O B Connector)		Control Supply	17
			Control Supply Connections	23
, P		48	Control Supply Connector	23
P		48	Mating Connector Part Numbers	23
P	Analog Output Pins on the Digital / Analog I/O B Connector		Wiring Specifications	23
A	Analog Output Specifications (Digital and Analog		cooling vents, inspecting	55
	I/O Connector)	47	Current Sinking Configuration with Isolation	31
Α	Analog Outputs (Digital and Analog I/O Connector)	47	Current Sinking Configuration without Isolation	31
A	Analog Outputs Schematic	47	Current Sourcing Configuration with Isolation	32
A	Axis 1 Encoder Input Pinout (Encoder Input Connector A)		Current Sourcing Configuration without Isolation	32
			D	
A	Axis 2 Encoder Input Pinout (Encoder Input Connector B) B Board Assembly		Declaration of Conformity	7
			Digital / Analog I/O Connectors	
-			Analog Inputs (Differential)	48
			Mating Connector Part Numbers	43
_	C	40	Digital and Analog I/O Connector	
	222483	49	Analog Outputs	47
	526263	49	Digital Inputs	46
C		00	Digital Outputs	44
	нурег Шиге	28	Digital and Analog I/O Connector A Pinout	43
	Sync Port	53		

Index

Digital and Analog I/O Connector B Pinout	43
Digital and Analog I/O Connectors	43
Digital Input Pins (Digital/Analog I/O B Connector)	46
Digital Input Specifications	46
Digital Inputs (Digital and Analog I/O Connector)	46
Digital Inputs Connected to Current Sinking Devices	46
Digital Inputs Connected to Current Sourcing Devices	46
Digital Output Pins (Digital/Analog I/O A Connector)	44
Digital Output Specifications	44
Digital Outputs (Digital and Analog I/O Connector)	44
Digital Outputs Connected in Current Sinking Mode	45
Digital Outputs Connected in Current Sourcing Mode	45
Dimensions	19
Drive and Software Compatibility	21
E	
Electrical Noise Suppression Devices	51
Electrical Specifications	17
EMC/CE Compliance	27
Emergency Stop Sense Input	51
Enclosure	18
Encoder Input Connections Schematic	50
Encoder Input Connectors	49
Mating Connector Part Numbers	49
Encoder Input Specifications	49
Encoder Output Connector	35
Mating Connector Part Numbers	35
Pinout	35
End of Travel Limit Input Connections	40

End of Travel Limit Input Interface	39
End of Travel Limit Input Pins on the Galvo Motor Connectors	39
End of Travel Limit Interface Input Schematic	40
End of Travel Limit Phasing	41
Environmental Specifications	20
ESTOP	51
ESTOP Pins on the Encoder Input Connector	51
ESTOP Sense Input Schematic (Encdoer Input Connector)	51
EU 2015/863	7
examining parts	
cables	55
connections	55
examining, dangerous fluids	55
examining, dangerous material	55
External Power Supply Options	25
F	
Feature Summary	15
Figure	
Analog Inputs Schematic	48
Analog Outputs Schematic	47
Control Board Assembly	56
Control Supply Connections	23
Current Sinking Configuration with Isolation	31
Current Sinking Configuration without Isolation	31
Current Sourcing Configuration with Isolation	32
Current Sourcing Configuration without	
ISUIAUUT	32
Digital Inputs Connected to Current Sinking Devices	32 46

Digital Outputs Connected in Current Sinking Mode	9 45
Digital Outputs Connected in Current Sourcing Mode	45
Dimensions	19
Encoder Input Connections Schematic	50
End of Travel Limit Input Connections	40
End of Travel Limit Input Schematic	40
ESTOP Sense Input Schematic	51
Laser Interface Outputs	30
Laser Output Polarity Switches	52
Motor Supply Connections	24
Power Board Assembly	57
Thermistor Interface Input Schematic	42
Third-Party Power Supply Connection 25	-26
TM3 Transformer Control and Power Wiring	25
TTL Output	33
fluids, dangerous	55
Functional Diagram	16
G	
Galvo Motor Connector	37
End of Travel Limit Input Interface	39
Galvo Motor Connectors	
Analog Encoder Inputs	38
Mating Connector Part Numbers	37
Pinout	37
Thermistor Interface	42
Global Technical Support	2
н	
Humidity	20
HyperWire	28
Cable Part Numbers	28
Card Part Number	28

I	
IFOV Cable	49
Input Power Connections	23
inspecting cooling vents	55
Inspection	55
Installation and Configuration	23
Introduction	15
IP54 Compliant	18
L	
Laser Interface Outputs	30
Laser Output A Connector	
Position Synchronized Output _ DriveType.XL4s [9]	34
PSO _DriveType.XL4s [9]	34
Laser Output Connector A Pinout	29
Laser Output Connector B Pinout	29
Laser Output Connectors	29
Mating Connector Part Numbers	29
Laser Output Polarity Switch	52
Laser Output Polarity Switches	52
Laser Output Specifications	30
Limit Input Diagnostic Display	41
м	
Maintenance	55
material, electrically conductive	55
Mating Connector P/N	
Control Supply Connector	23
Digital / Analog I/O Connectors	43
Encoder Input Connectors	49
Encoder Output Connector	35
Galvo Motor Connectors	37
Laser Output Connectors	29
Motor Supply Connector	24

Mechanical Specifications	18
Minimizing Conducted, Radiated, and System Noise for EMC/CE Compliance	27
Minimum Load Resistance	17
Motor Supply	17
Motor Supply Connections	24
Motor Supply Connector	24
Mating Connector Part Numbers	24
Motor Supply Wiring Specifications	24
Mounting and Cooling	18
Mounting Hardware	18
Mounting Orientation	18
ο	
Operation	20
Output Voltage	17
Overview	15
Р	
PC Configuration and Operation Information	54
Peak Output Current	17
Phasing	
End of Travel Limits	41
Pinout	
Analog Input Pins (Digital / Analog I/O B Connector)	48
Analog Output Pins (Digital / Analog I/O B Connector)	47
Axis 1 Encoder Inputs (Encoder Input Connector A)	49
Axis 2 Encoder Inputs (Encoder Input Connector B)	49
Digital and Analog I/O Connector A	43
Digital and Analog I/O Connector B	43

Digital Input Pins (Digital/Analog I/O B Connector)

Digital Output Pins (Digital/Analog I/O A Connector)	44	
Encoder Output Connector	35	
End of Travel Limit Input Pins (Galvo Motor Connectors)	39	
ESTOP Pins on the Encoder Input Connector	51	
Galvo Motor Connectors	37	
Laser Output Connector A	29	
Laser Output Connector B	29	
PSO pins (Laser Output A Connector)	34	
PSO pins (Laser Output B Connector)	34	
Thermistor Interface Pins on the Galvo Motor Connectors	42	
Pollution	20	
Position Synchronized Output (PSO)	34	
Power Board Assembly	57	
Power Board Fuse Specifications	57	
Power Supply Options	25	
Preventative Maintenance	55	
PSO	34	
PSO External Sync Specifications	36	
PSO Output 29	,34	
PSO Pins on the Laser Output A Connector	34	
PSO Pins on the Laser Output B Connector	34	
PSO Specifications	34	
Q		
Quick Installation Guide	13	
Quick Start Connections	13	
R		
Revision History	61	
S		
Safety Procedures and Warnings	11	
Specifications		

Analog Encoder (Galvo Motor Connectors) 38

46

Analog Input (Digital / Analog I/O B Connector)	48
Analog Output (Digital and Analog I/O Connector)	47
Control Board Fuses	56
Control Supply Connector Wiring	23
Digital Inputs	46
Digital Outputs	44
Encoder Inputs	49
Laser Outputs	30
Motor Supply Wiring	24
Power Board Fuses	57
PSO	34
Unit Weight	18
Standard Features	15
Support	2
Sync-Related Commands	53
Sync Port Cables	53
Sync Ports	53
т	
Table of Contents	3
Technical Support	2
Thermistor Interface (Galvo Motor Connectors)	42
Thermistor Interface Input Schematic	42
Thermistor Interface Pins on the Galvo Motor Connectors	42
Third-Party Power Supply Connection	26
TM3 Transformer Control and Power Wiring	25
TTL Output	33
U	
Unit Weight	18
Use	20
User Power Supply Output	17

w

Warranty and Field Service 59

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